

Generative models

Neural Networks Design And Application

Machine learning paradigm



Training data

ML model for
panda recognition



Testing data

Machine learning paradigm



x

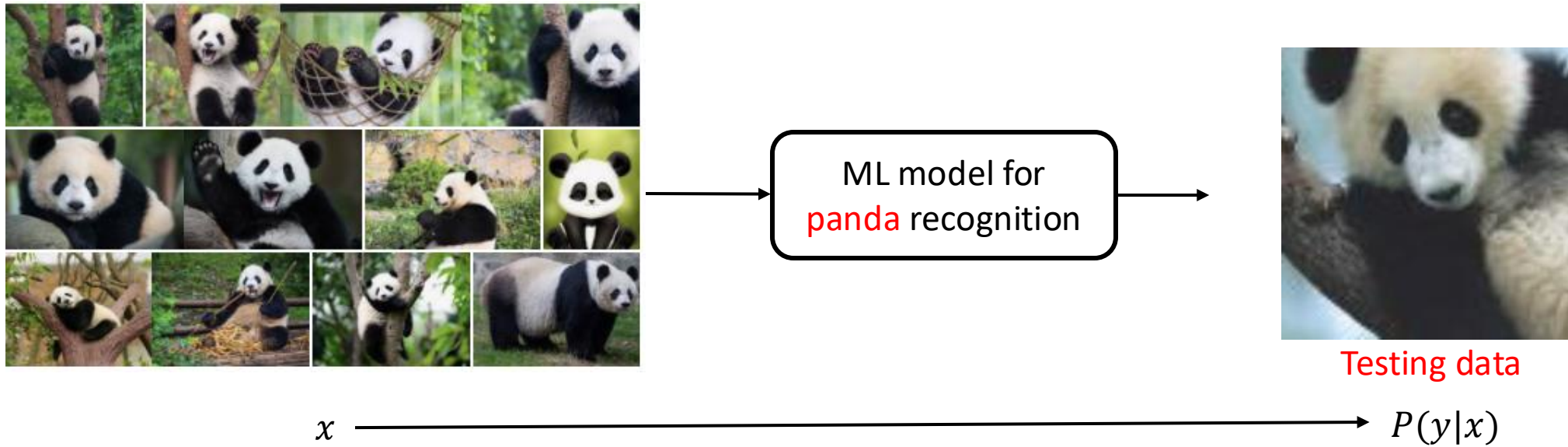
Training data

ML model for
panda recognition



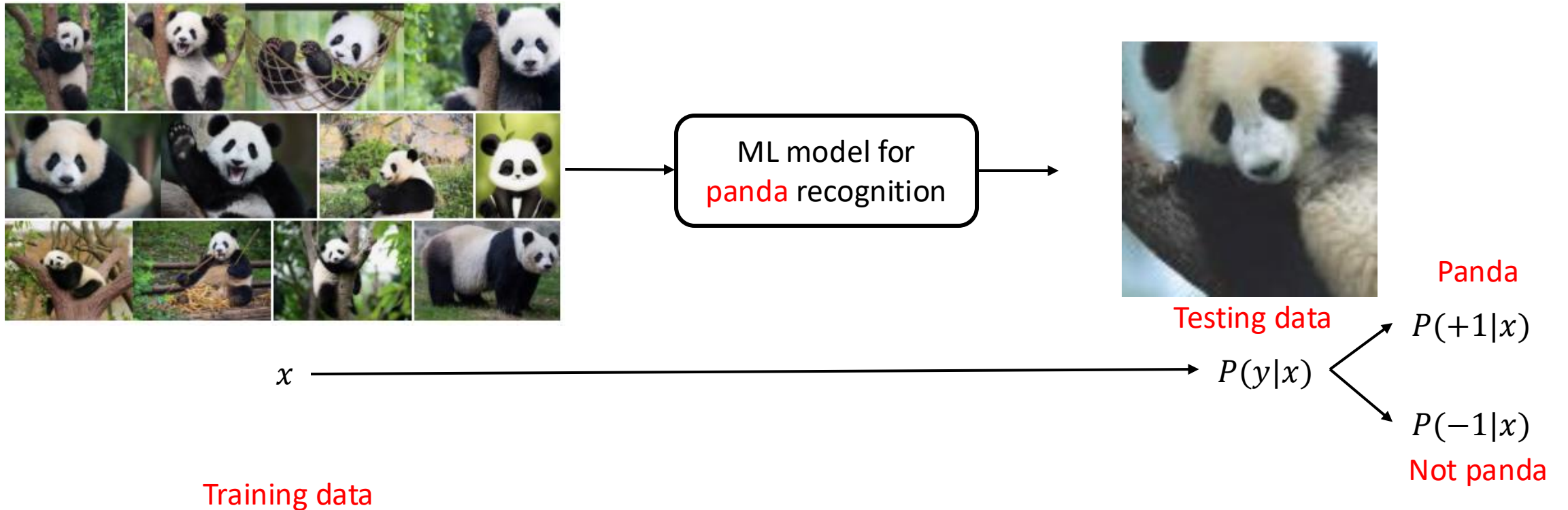
Testing data

Machine learning paradigm



Training data

Machine learning paradigm



Machine learning paradigm



ML model for **panda** recognition



Panda

Testing data

x

mapping

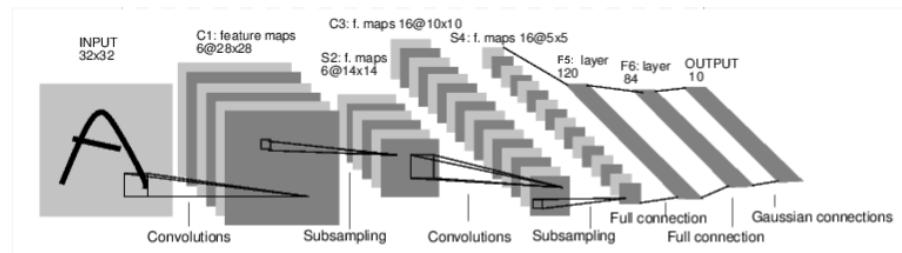
$P(y|x)$

$P(+1|x)$

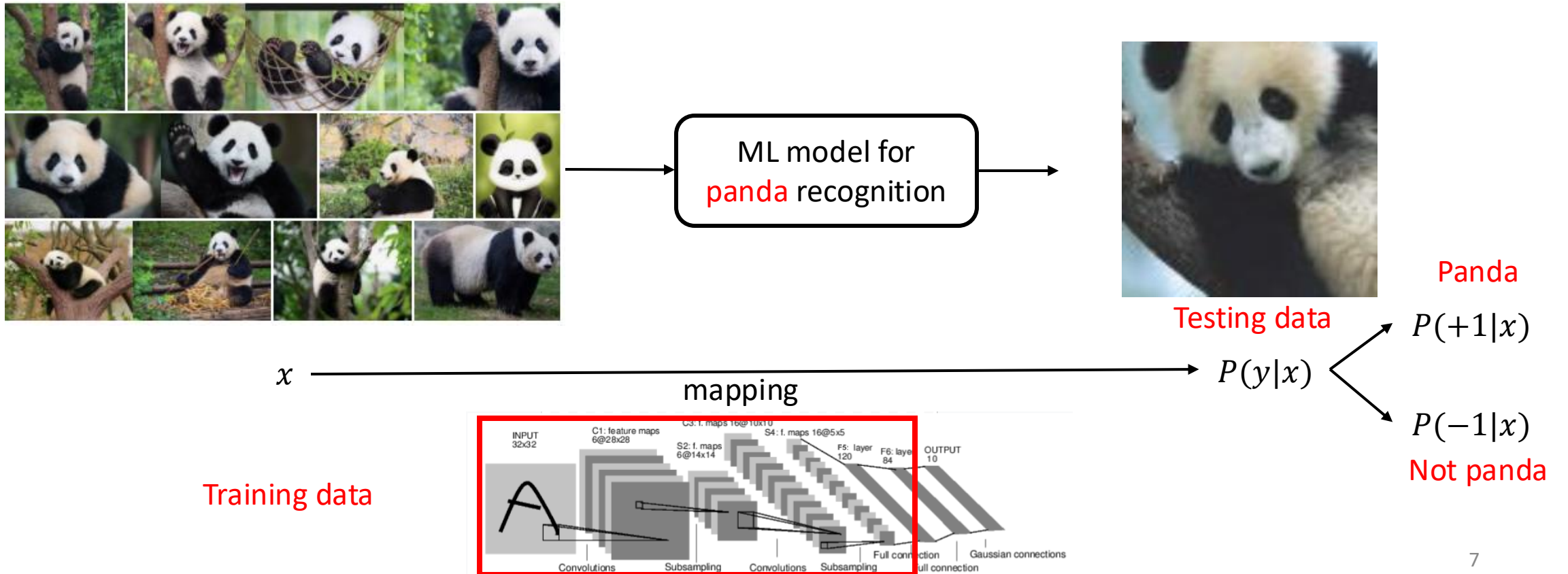
$P(-1|x)$

Not panda

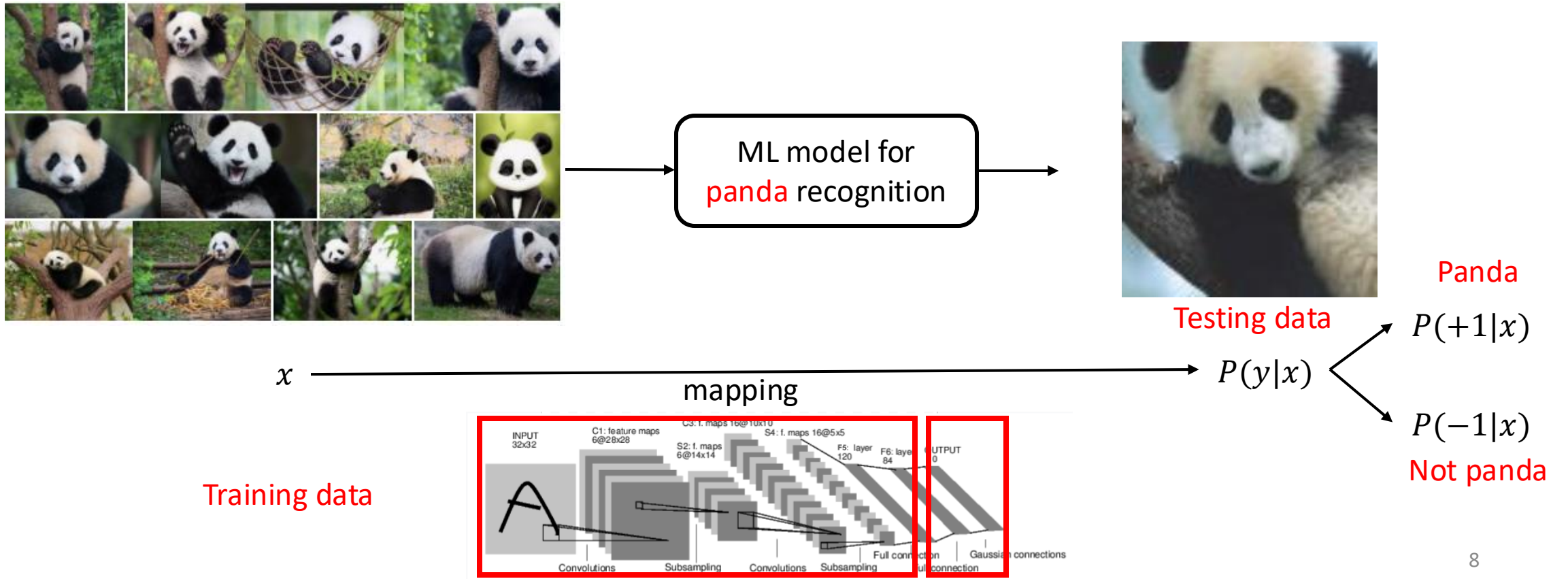
Training data



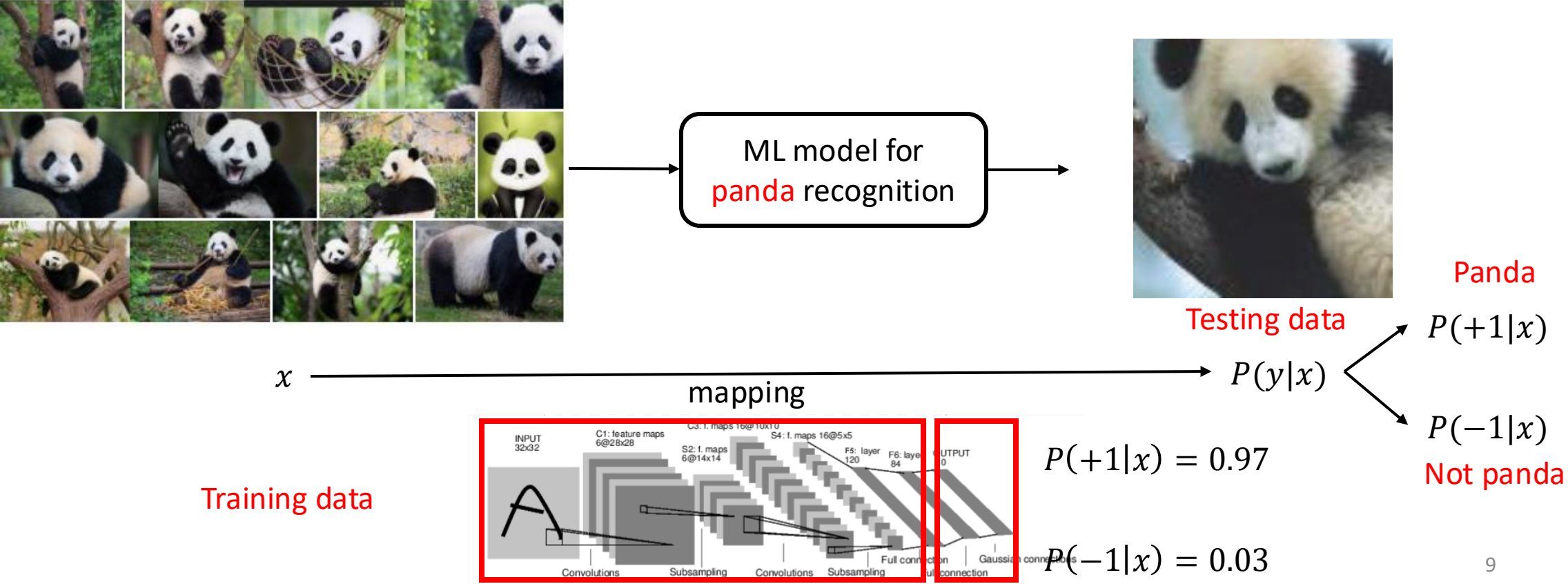
Machine learning paradigm



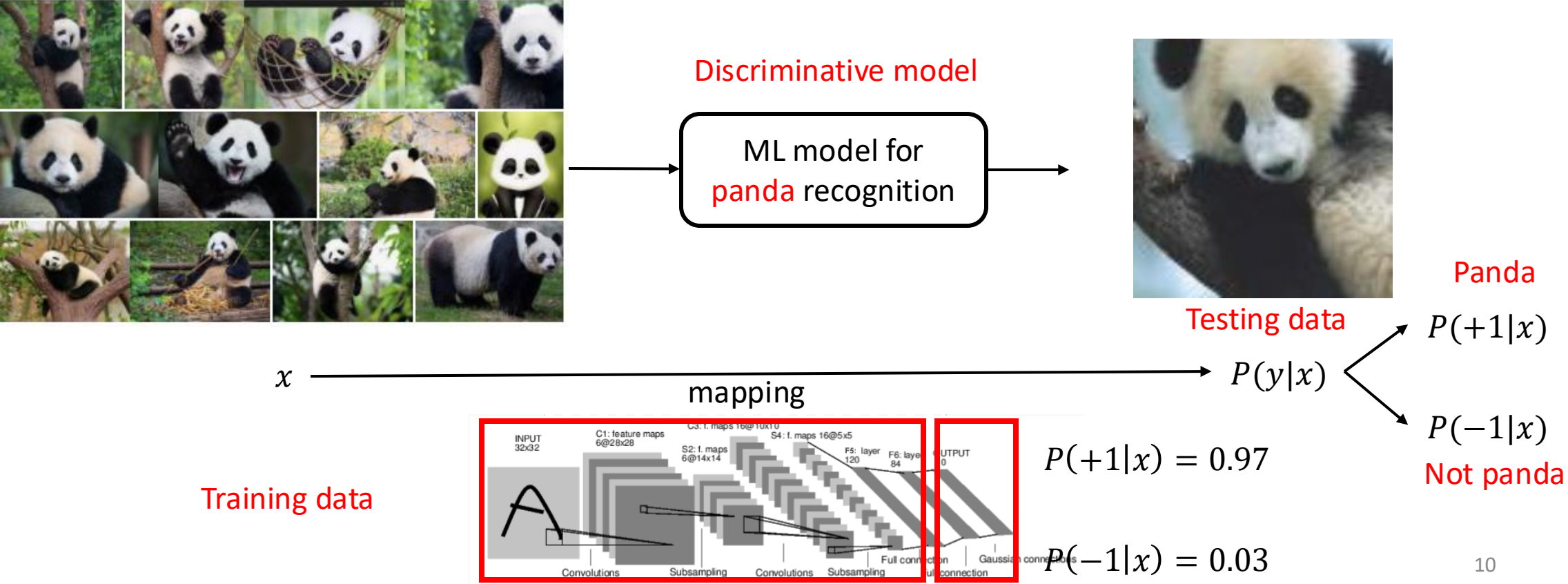
Machine learning paradigm



Machine learning paradigm



Machine learning paradigm

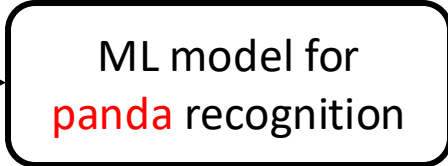


Machine learning paradigm

Q: other way for classification?



Discriminative model



Panda

Testing data

x

mapping

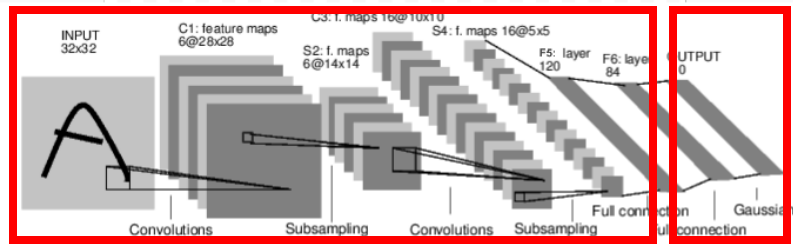
$P(y|x)$

$P(+1|x)$

$P(-1|x)$

Not panda

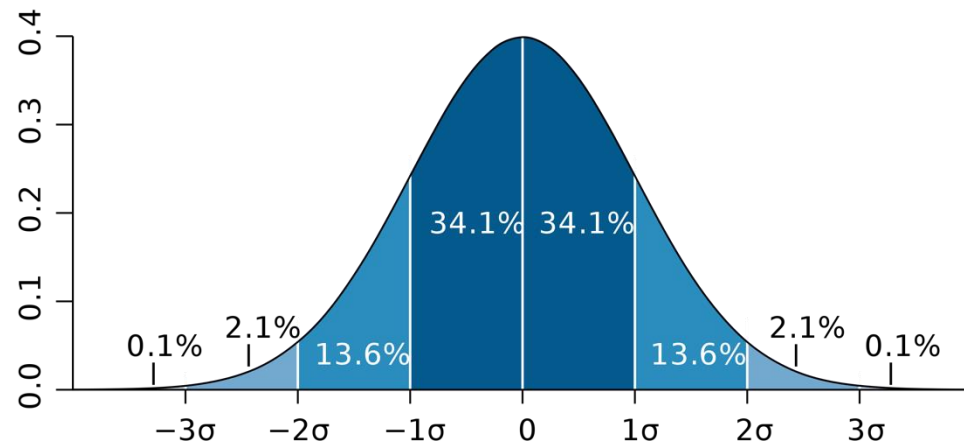
Training data



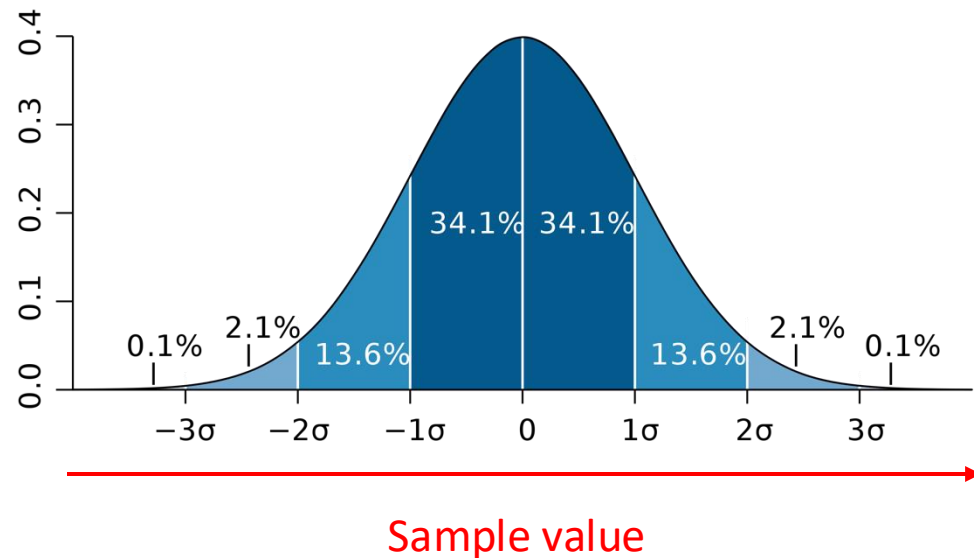
$$P(+1|x) = 0.97$$

$$P(-1|x) = 0.03$$

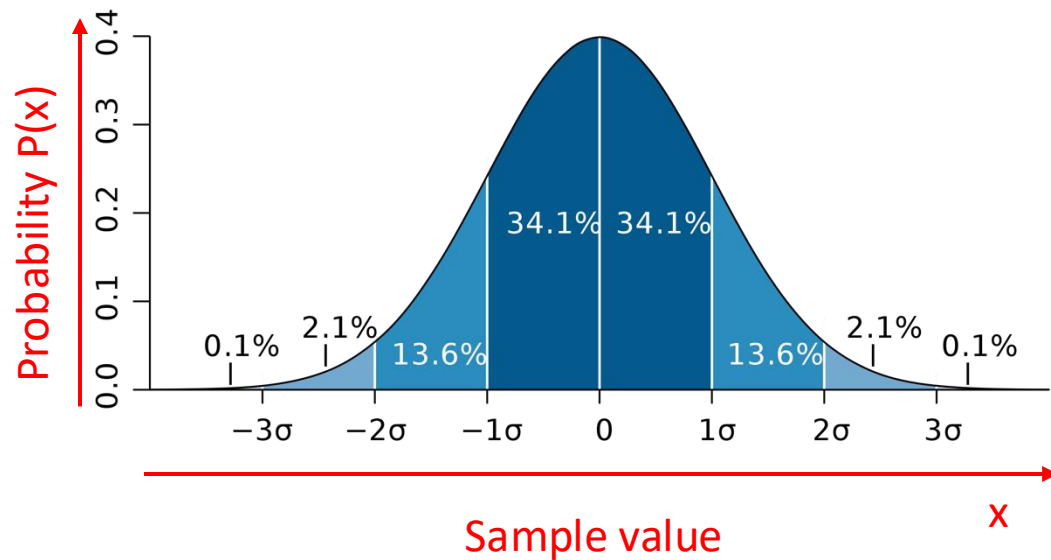
What is a probability distribution?



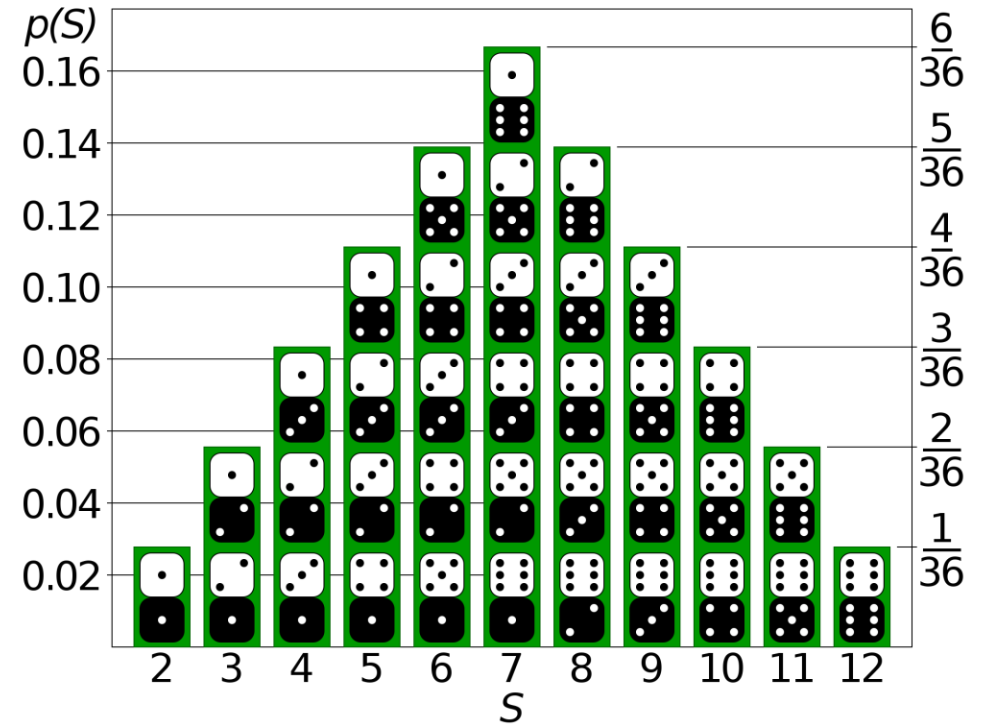
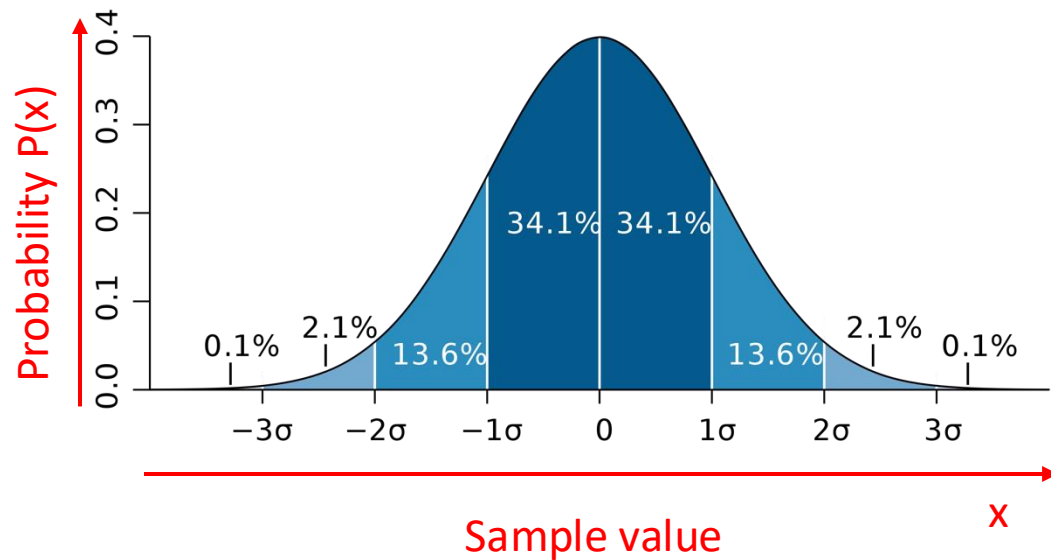
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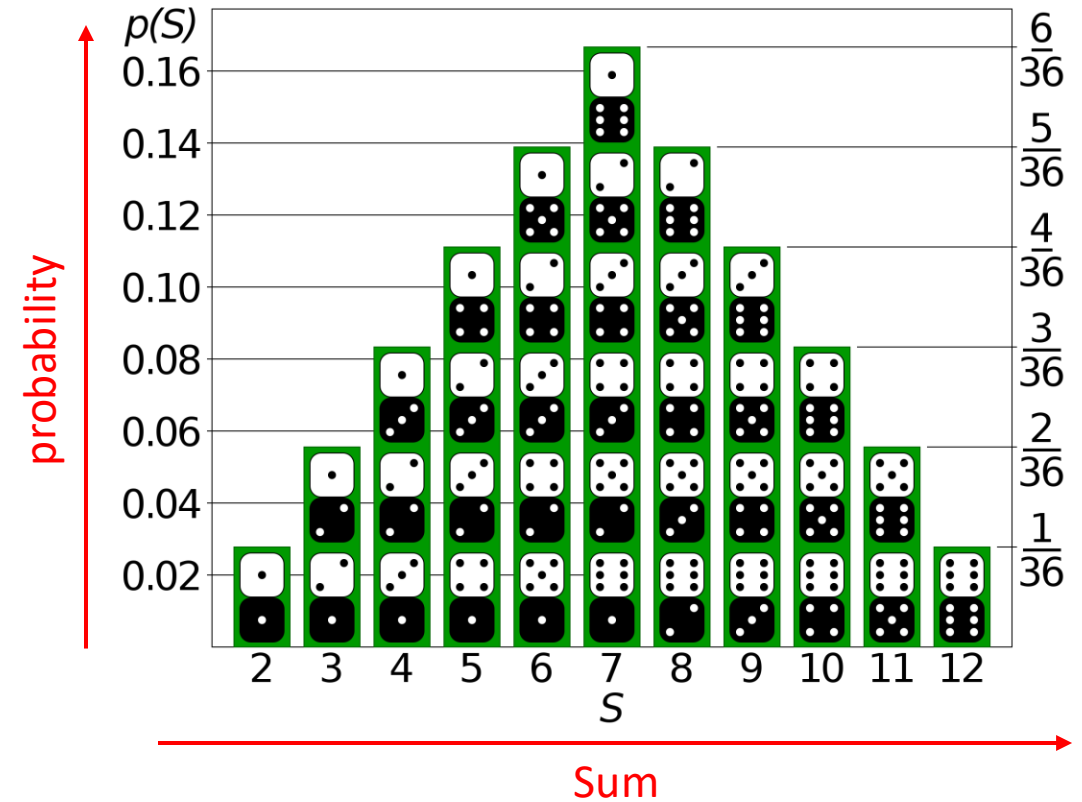
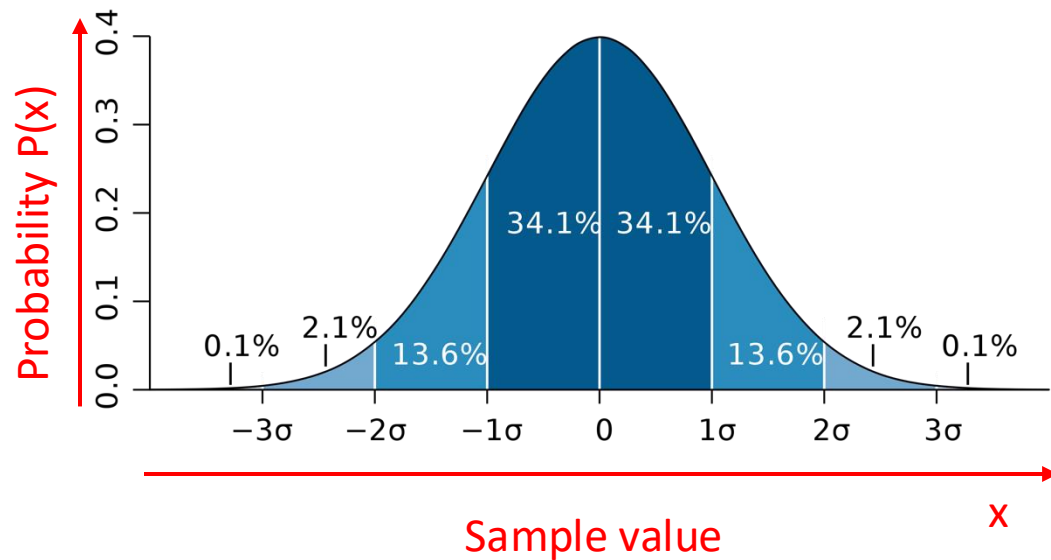
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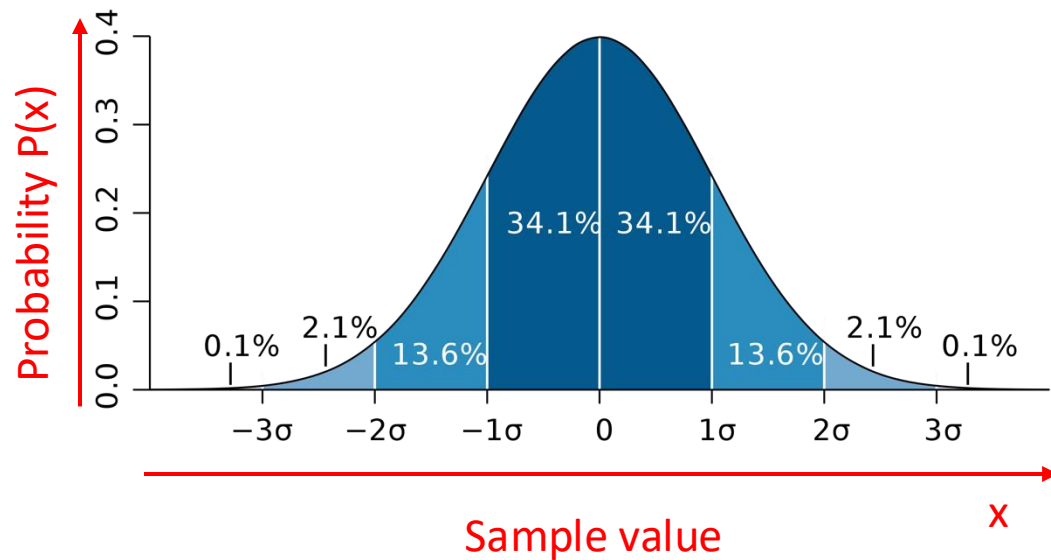
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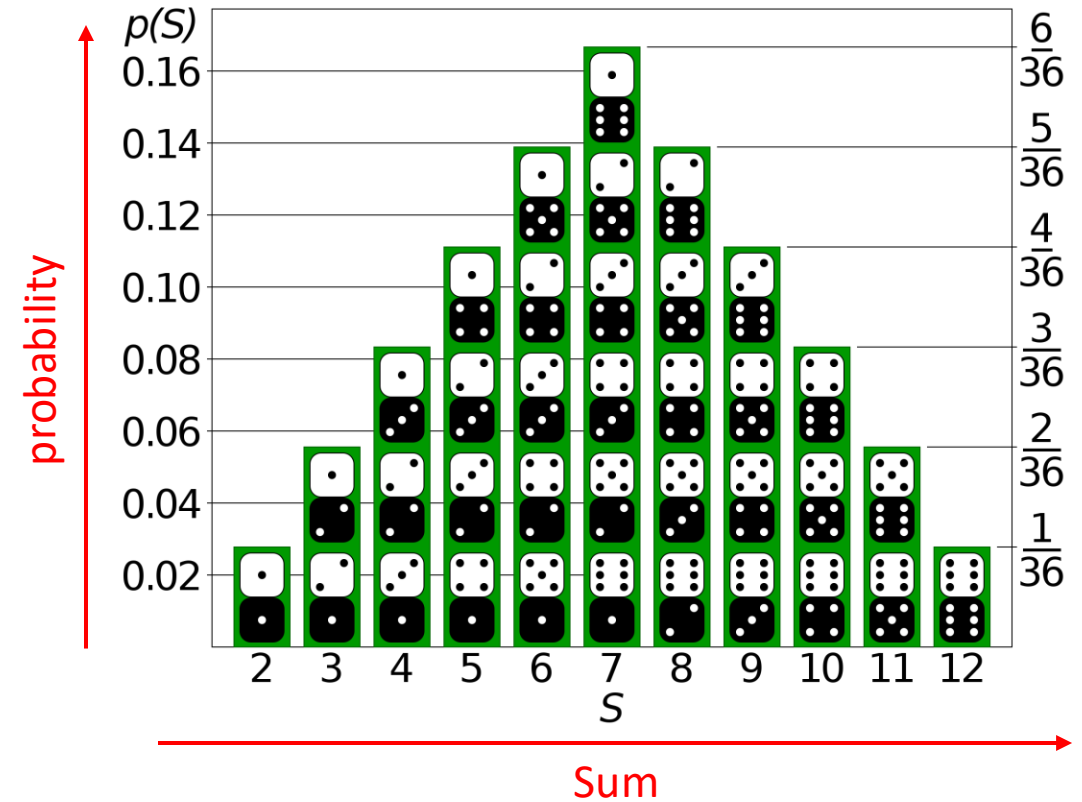
What is a probability distribution?



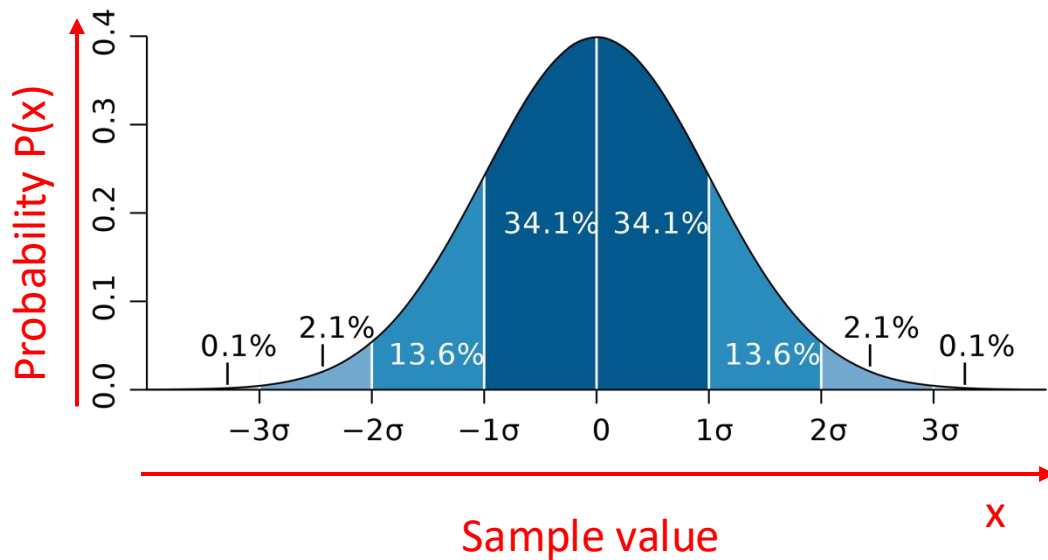
What is a probability distribution?



$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

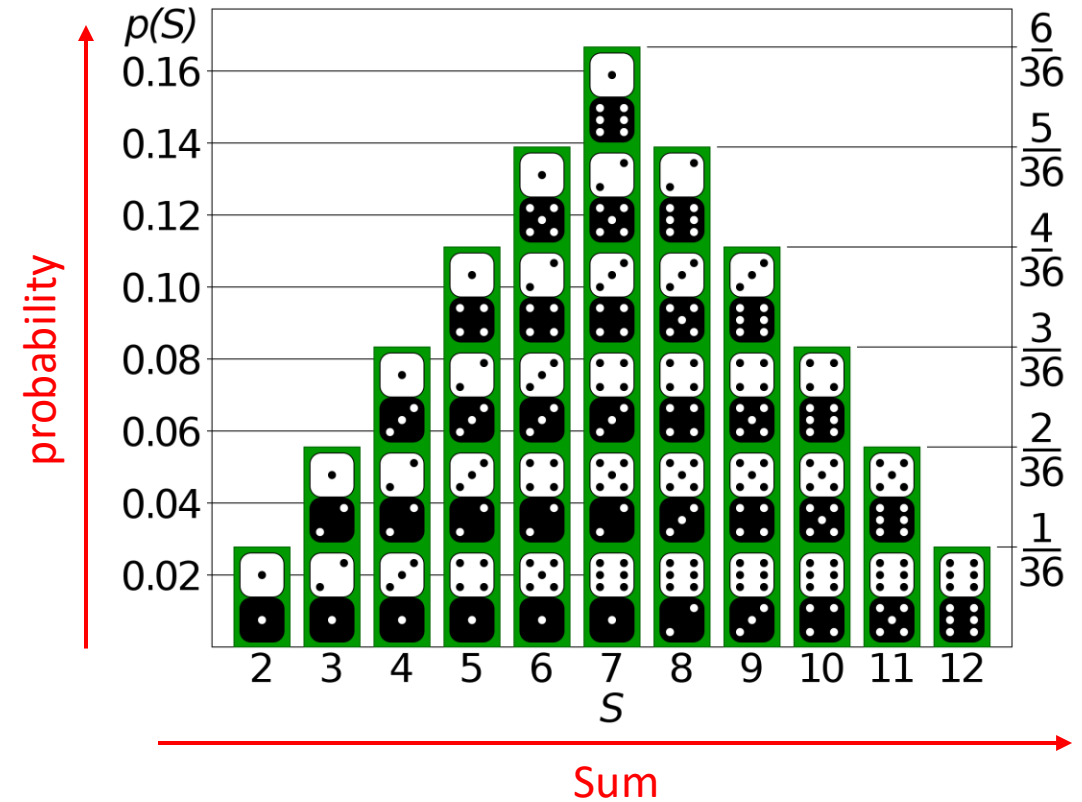


What is a probability distribution?

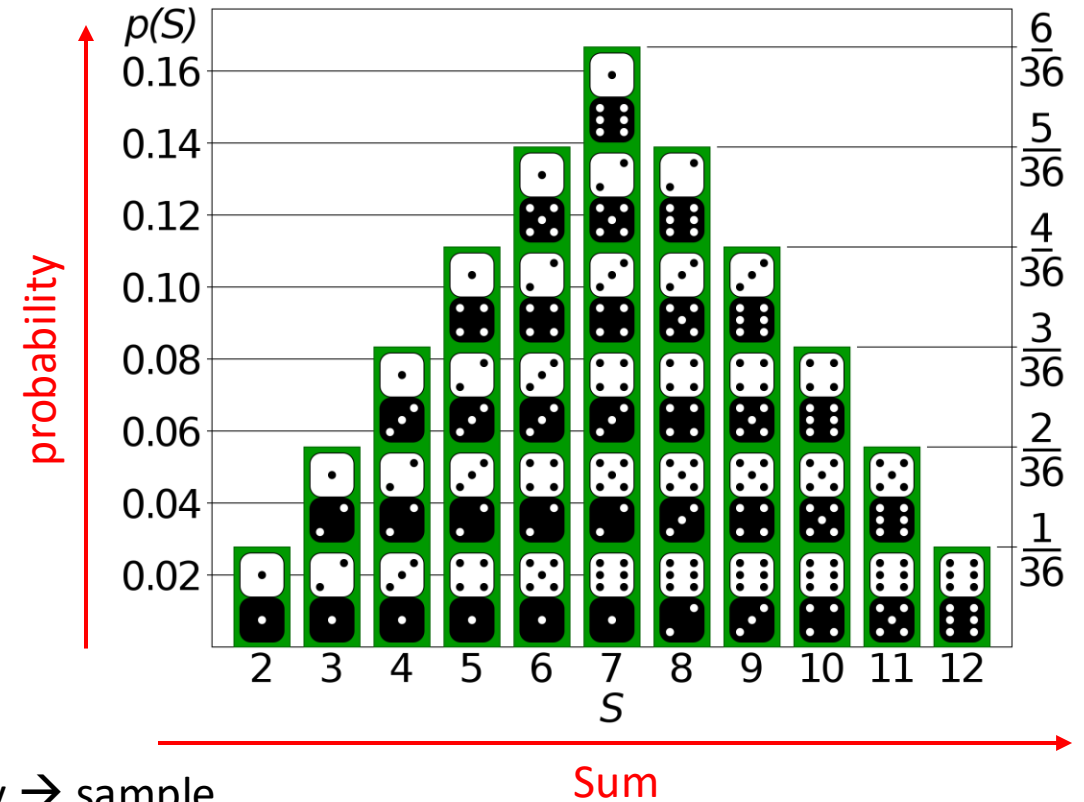
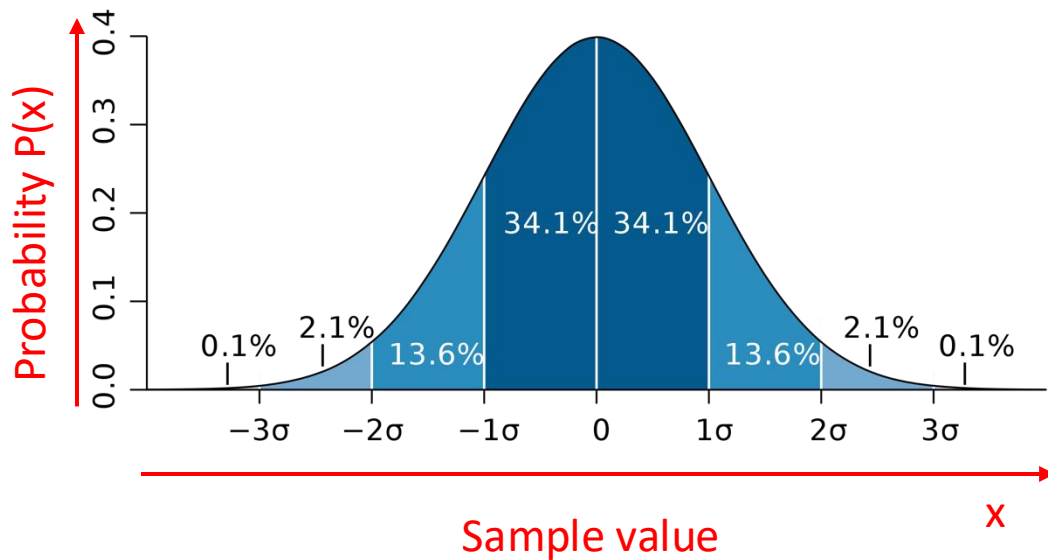


$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2} \longrightarrow f^{-1}$$

Inverse distribution function



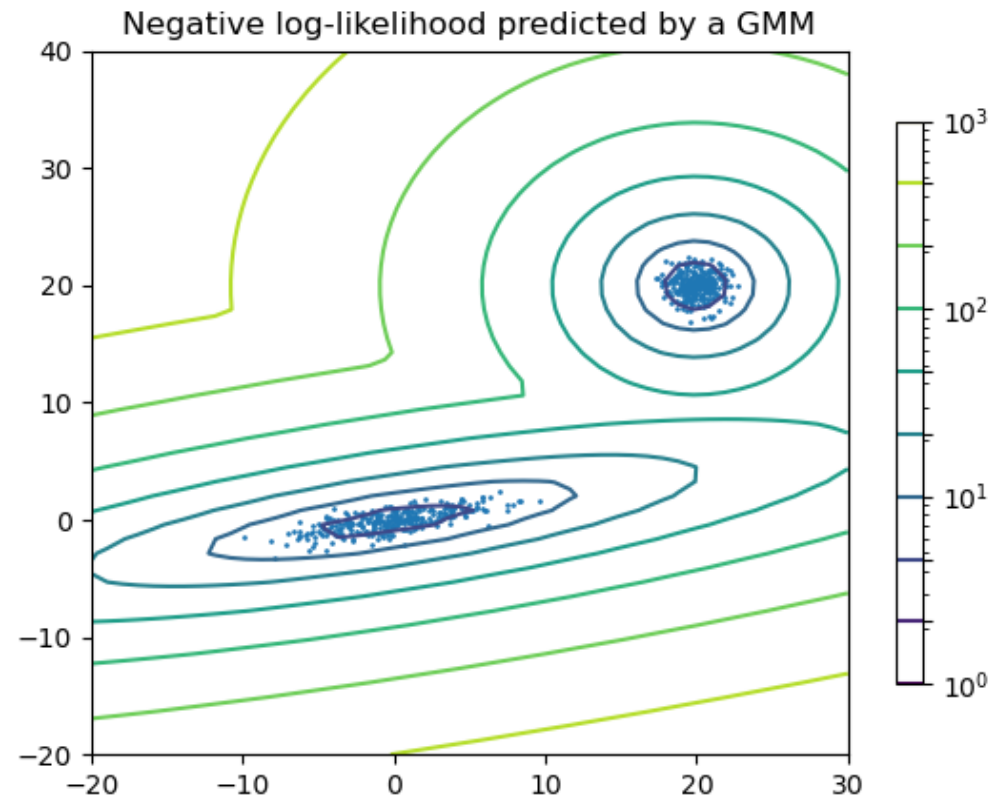
What is a probability distribution?



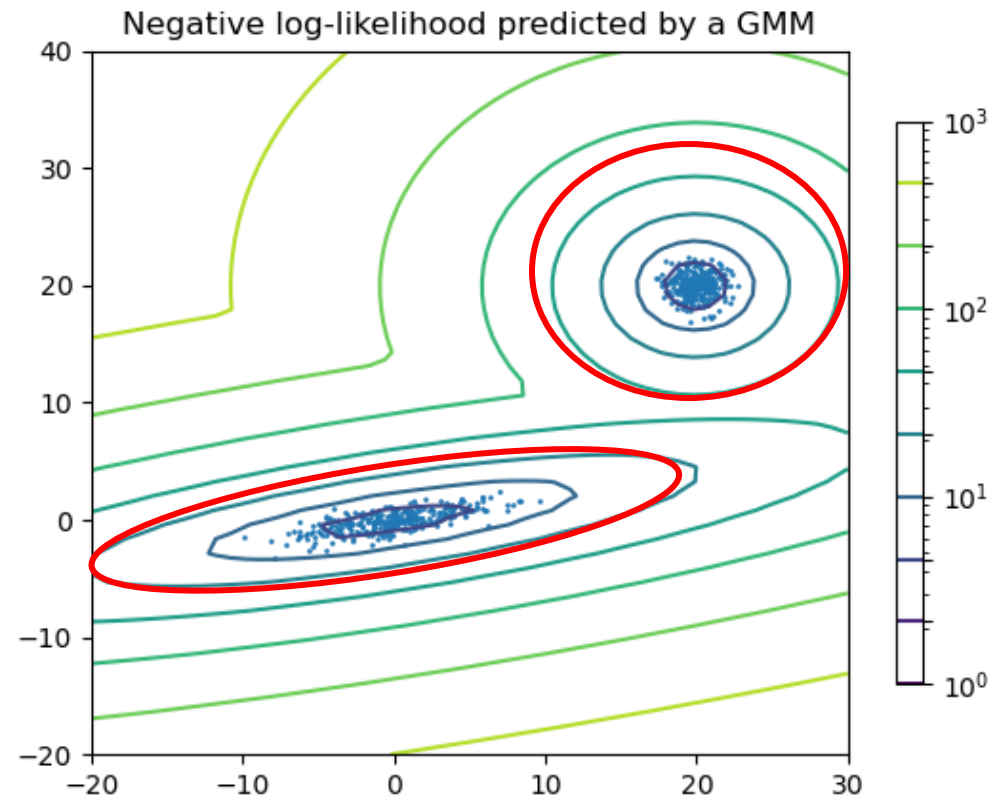
$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2} \longrightarrow f^{-1} \longrightarrow \text{Probability} \rightarrow \text{sample}$$

Inverse distribution function

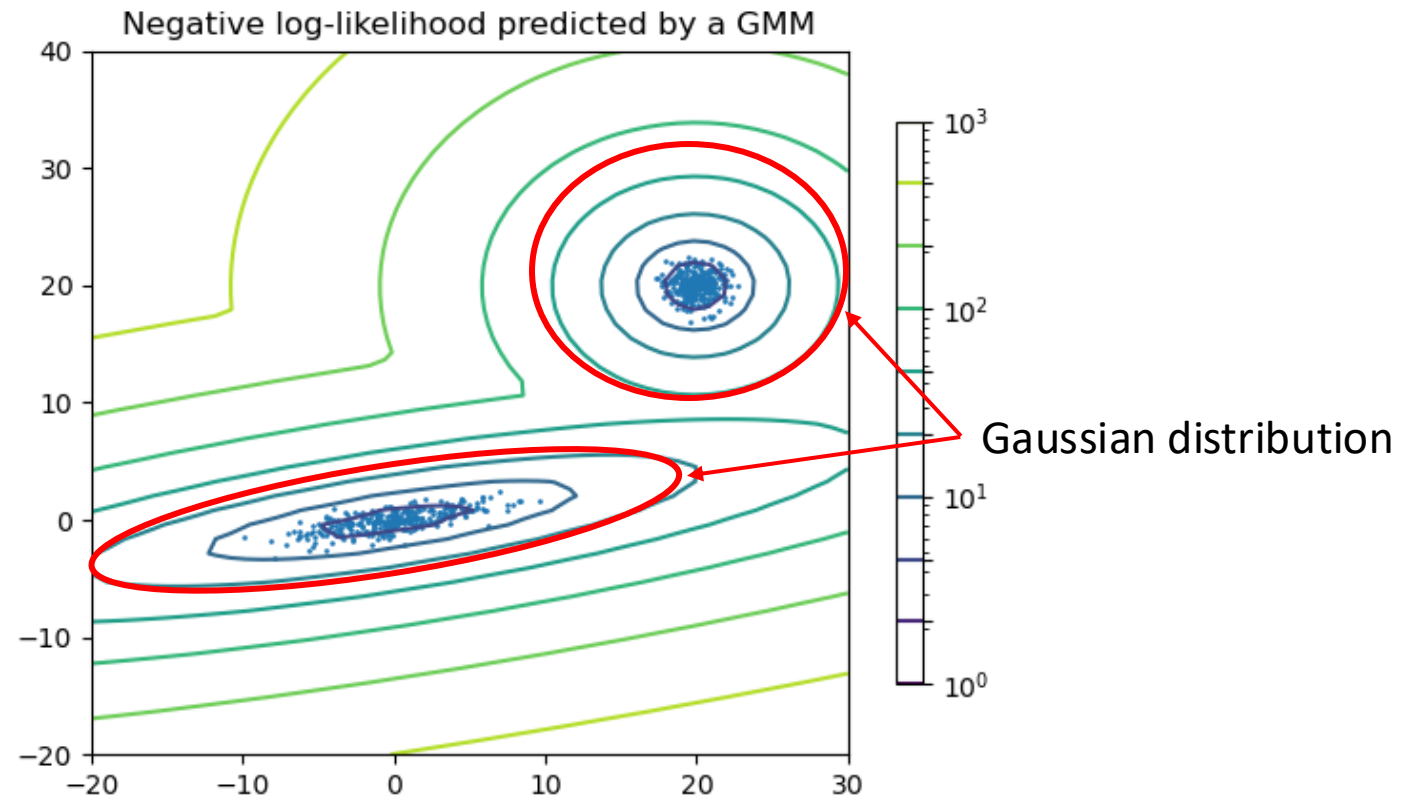
Gaussian mixture model



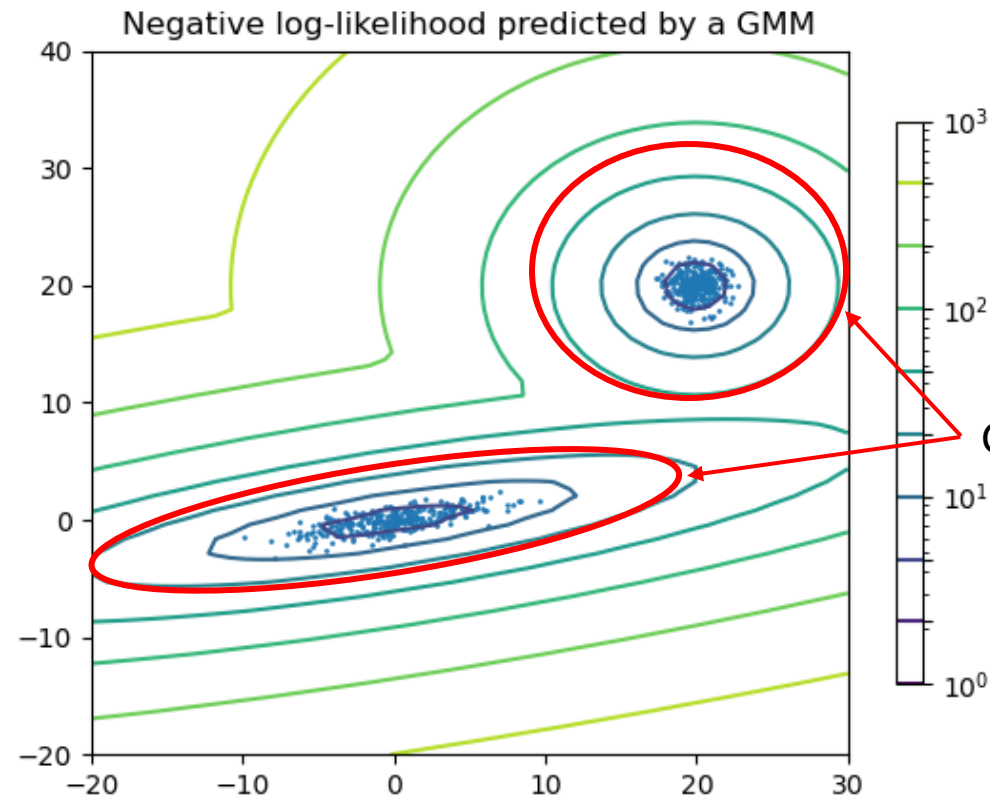
Gaussian mixture model



Gaussian mixture model



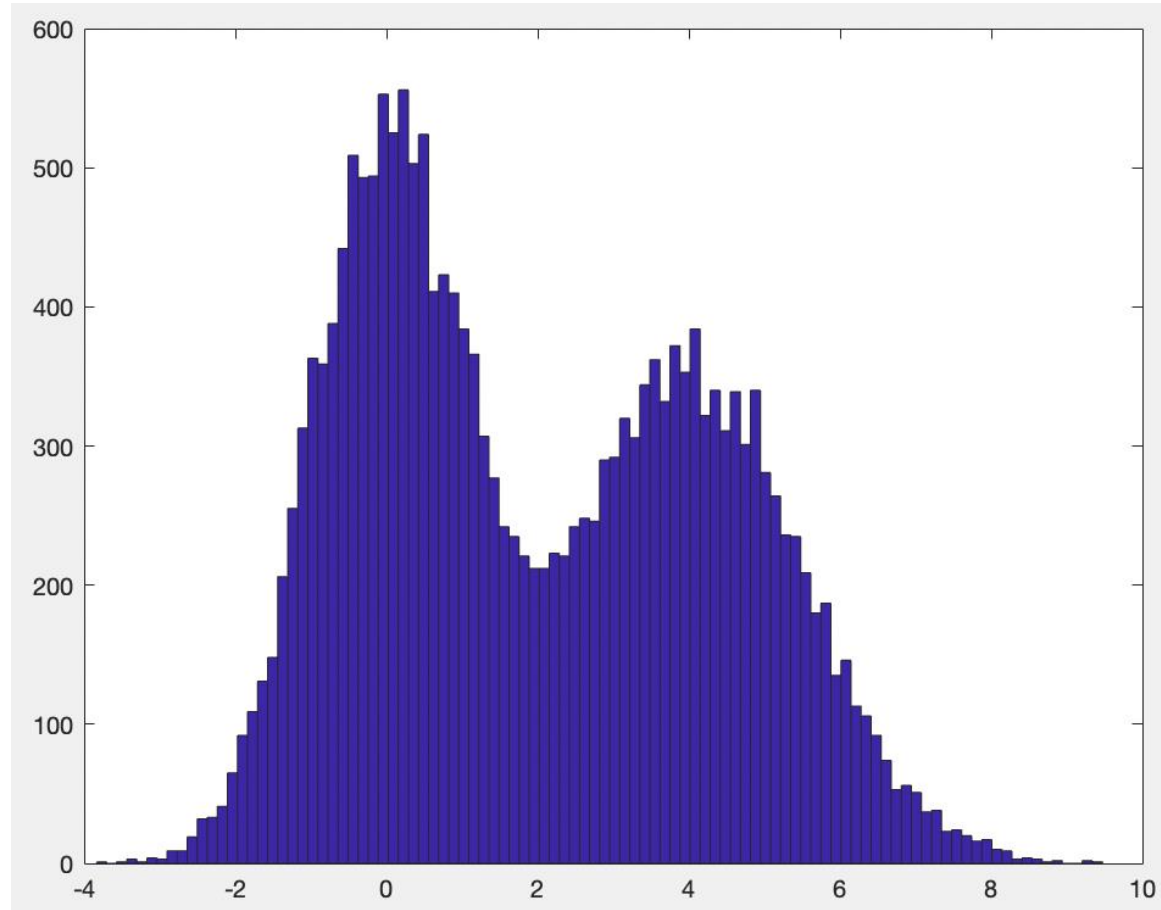
Gaussian mixture model



$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

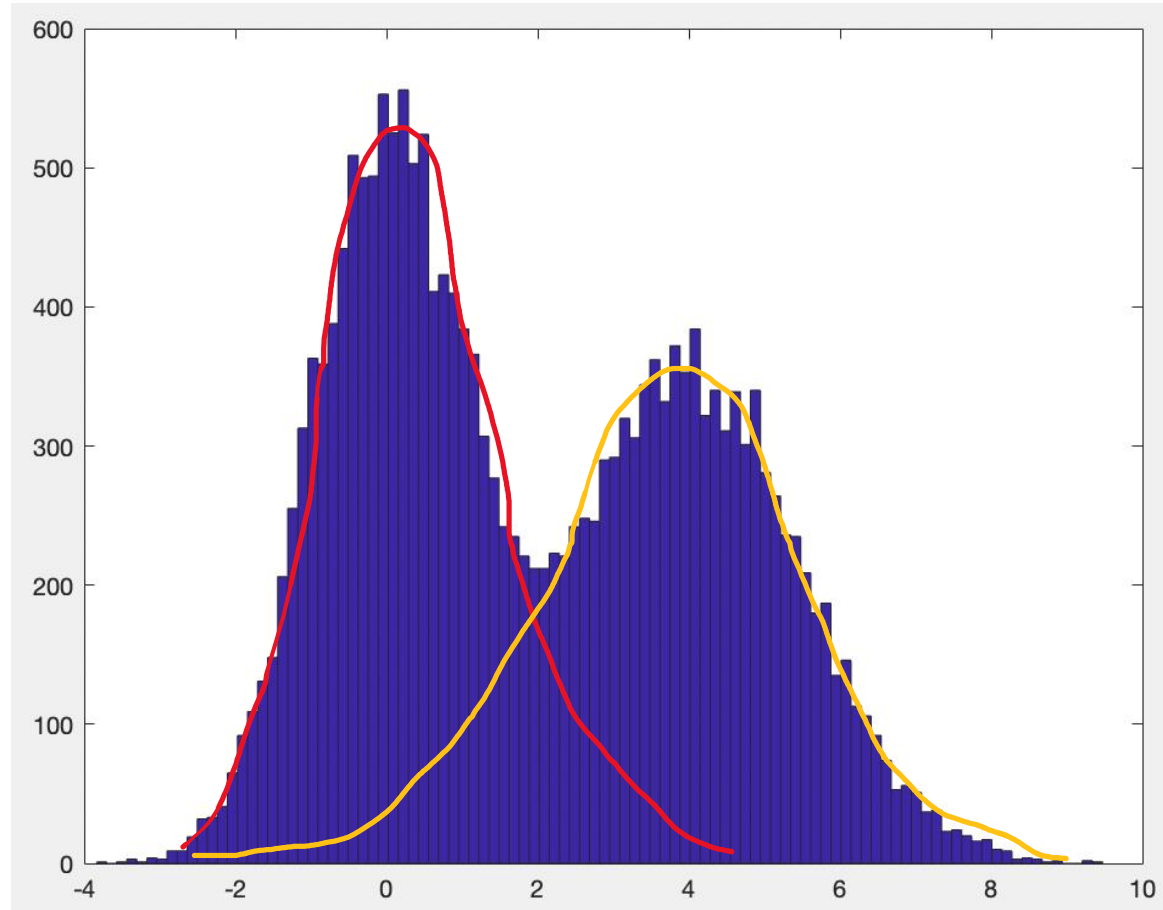
Gaussian distribution

Gaussian mixture model



Q: how many Gaussian distributions?

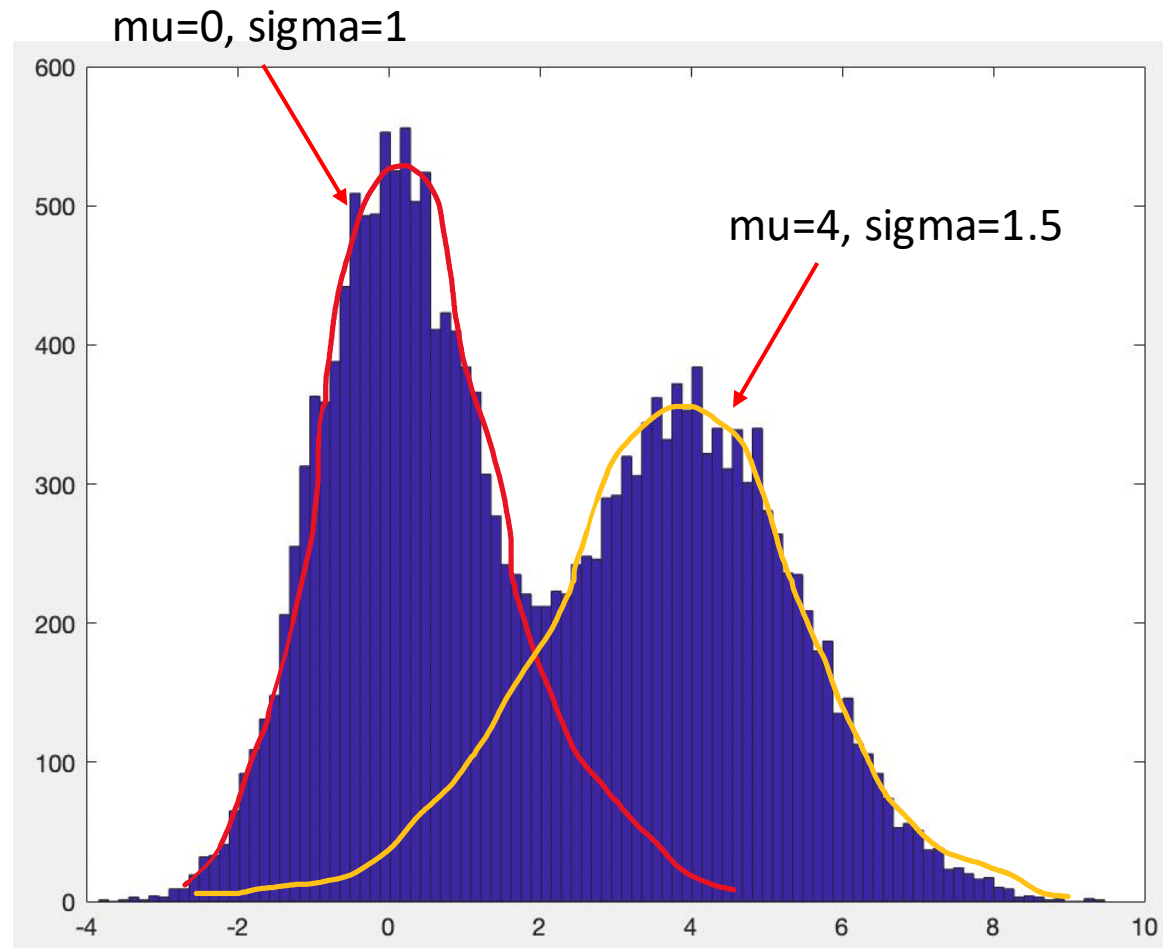
Gaussian mixture model



Q: how many Gaussian distributions?

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

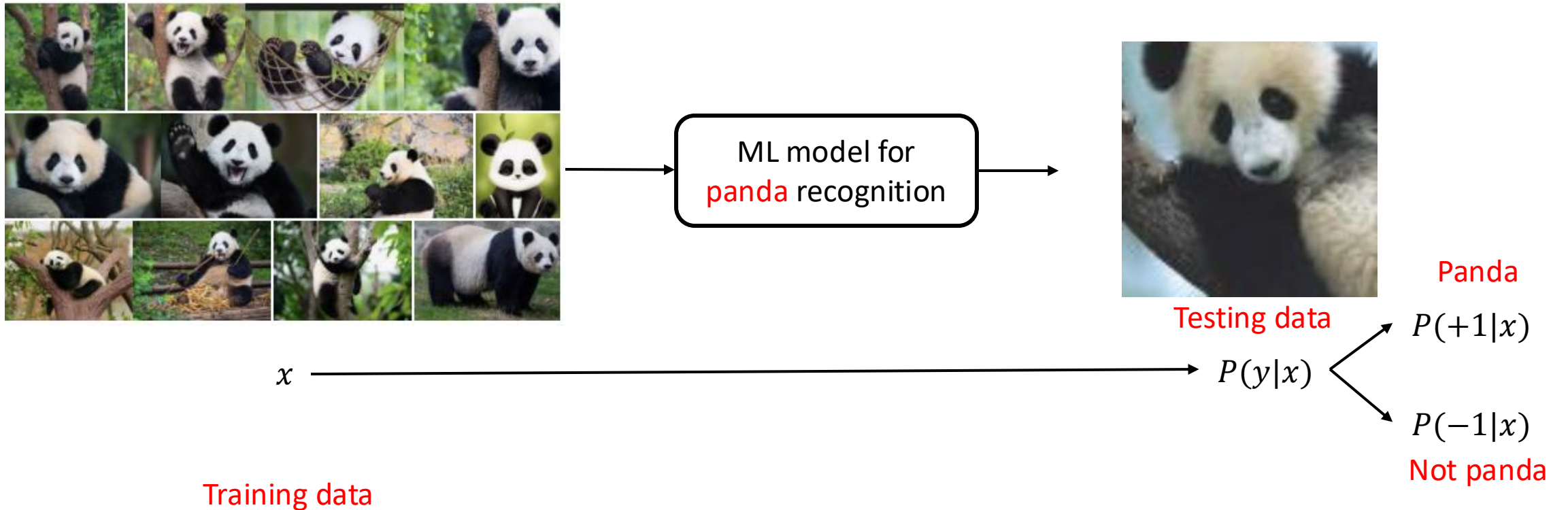
Gaussian mixture model



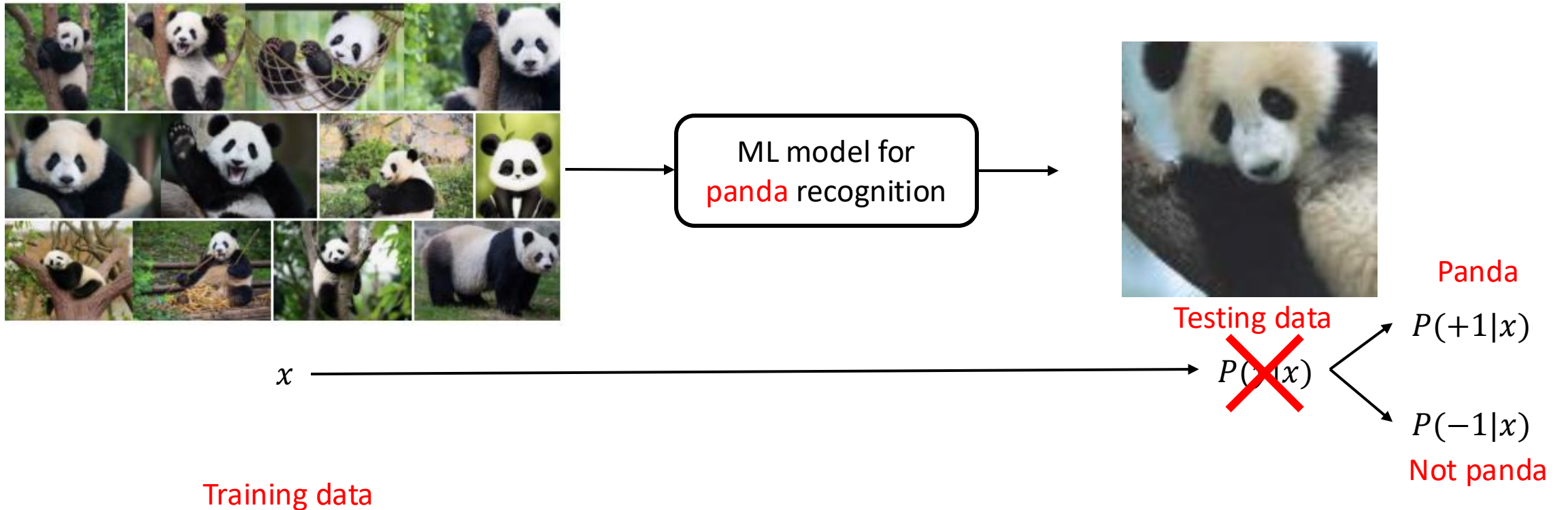
$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

Q: how many Gaussian distributions?

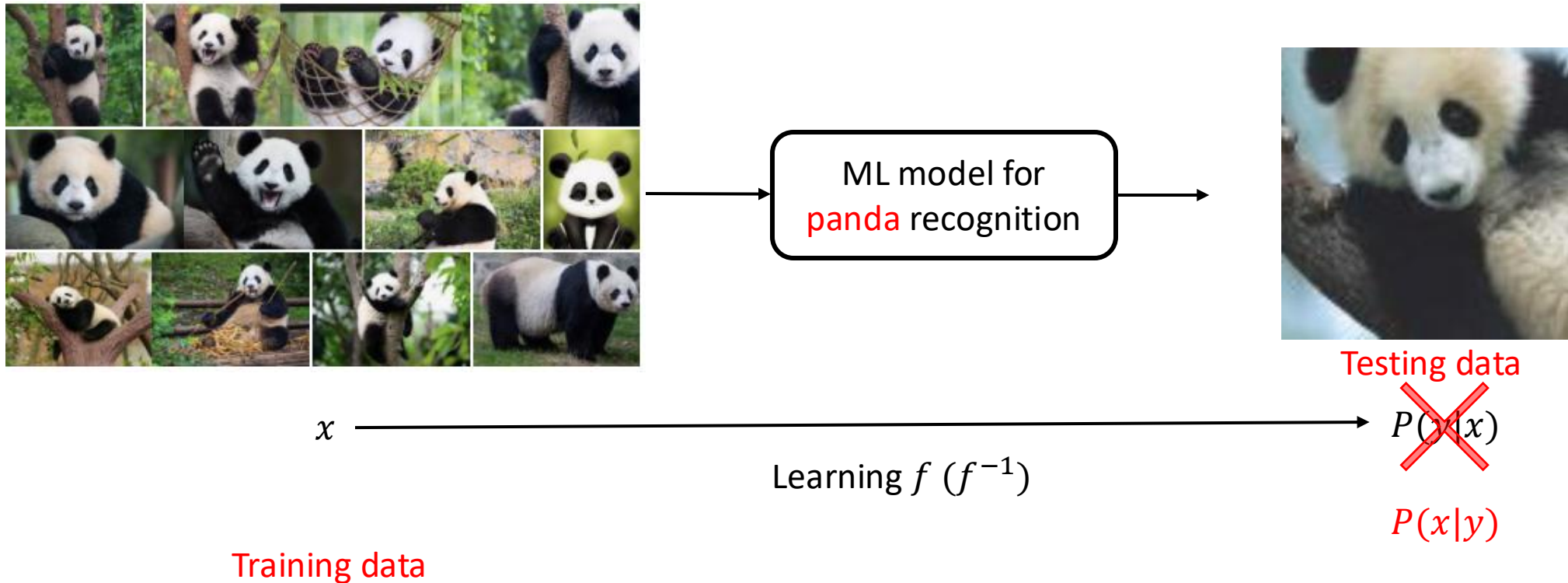
Machine learning paradigm



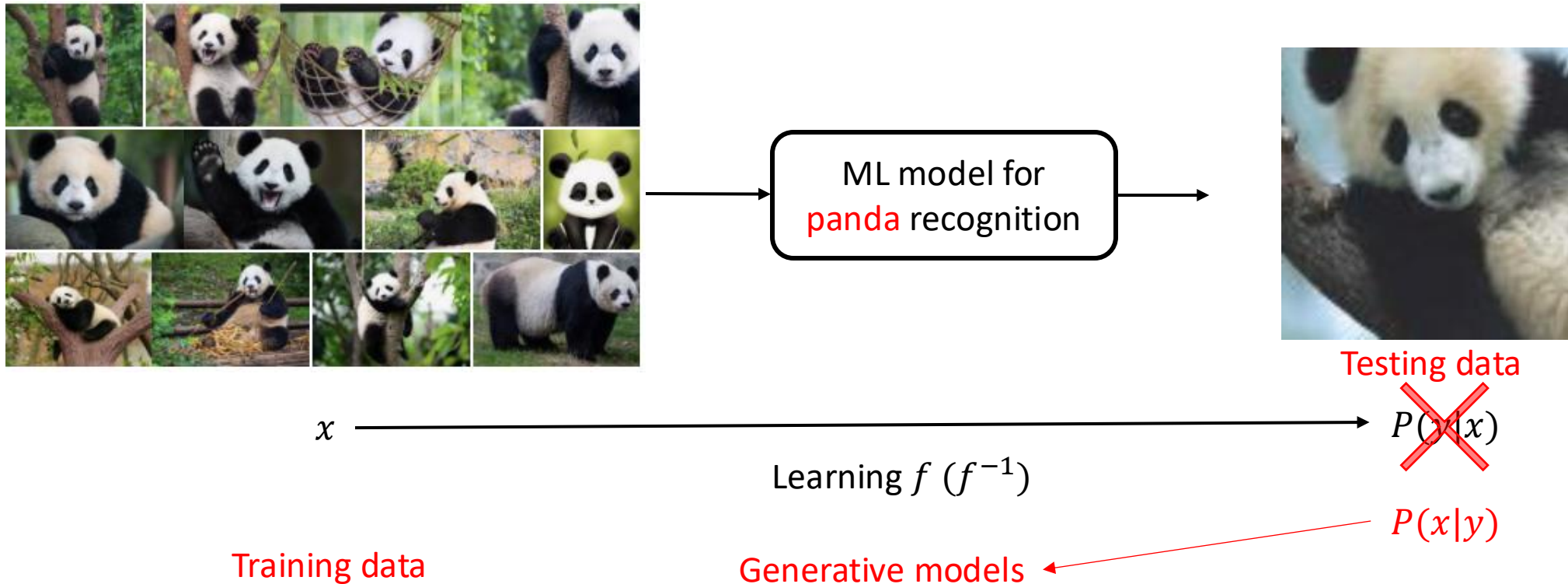
Machine learning paradigm



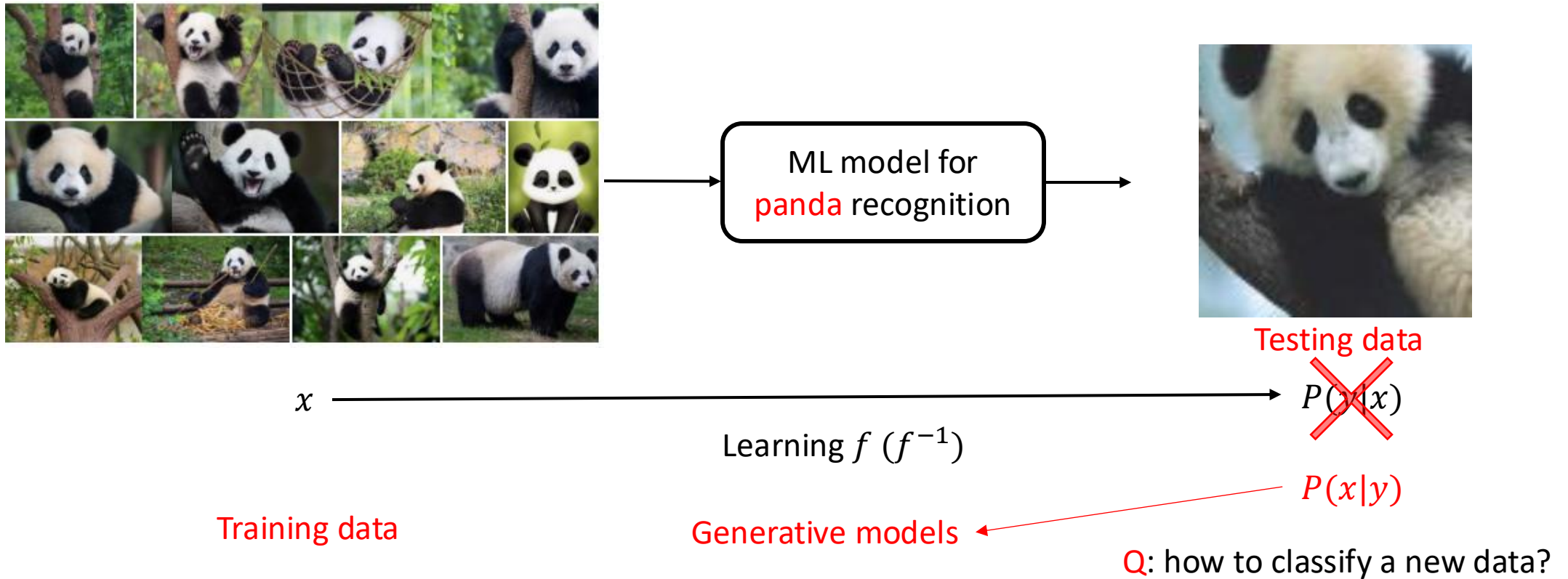
Machine learning paradigm



Machine learning paradigm



Machine learning paradigm



Machine learning paradigm

$$P(x', y) = P(x'|y)P(y)$$



ML model for
panda recognition



x

Testing data

~~$P(y|x)$~~

Learning $f (f^{-1})$

$P(x|y)$

Training data

Generative models

Q: how to classify a new data?

Machine learning paradigm

$$P(x', y) = P(x'|y)P(y)$$

Pick the label y with largest $P(x', y)$



ML model for
panda recognition



Testing data

~~$P(y|x)$~~

Learning $f (f^{-1})$

Training data

Generative models

$P(x|y)$

Q: how to classify a new data?

Machine learning paradigm

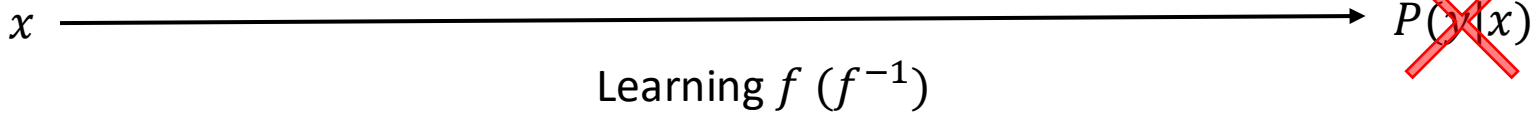
$$\begin{aligned}
 P(x', +1) &= P(x'|+1)P(+1) \\
 P(x', -1) &= P(x'|-1)P(-1)
 \end{aligned}$$

$$P(x', y) = P(x'|y)P(y)$$

Pick the label y with largest $P(x', y)$



ML model for **panda** recognition



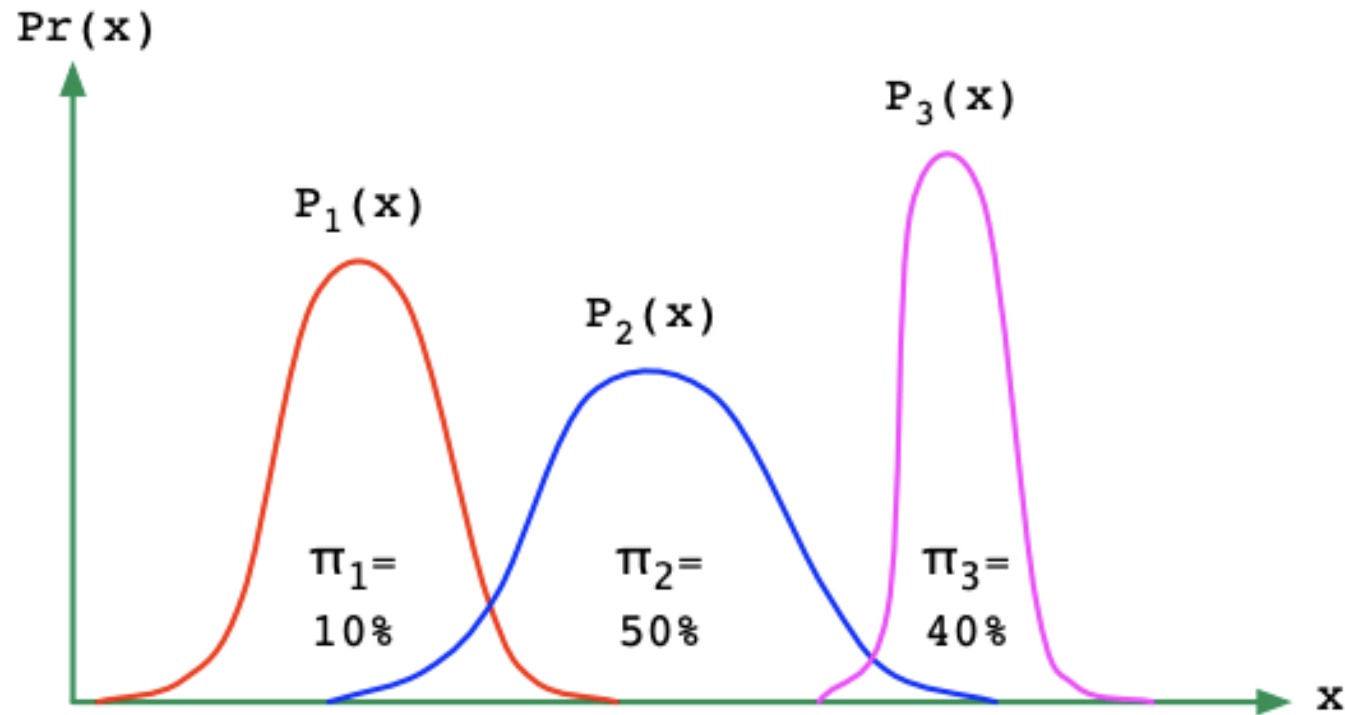
Training data

Generative models

$P(x|y)$

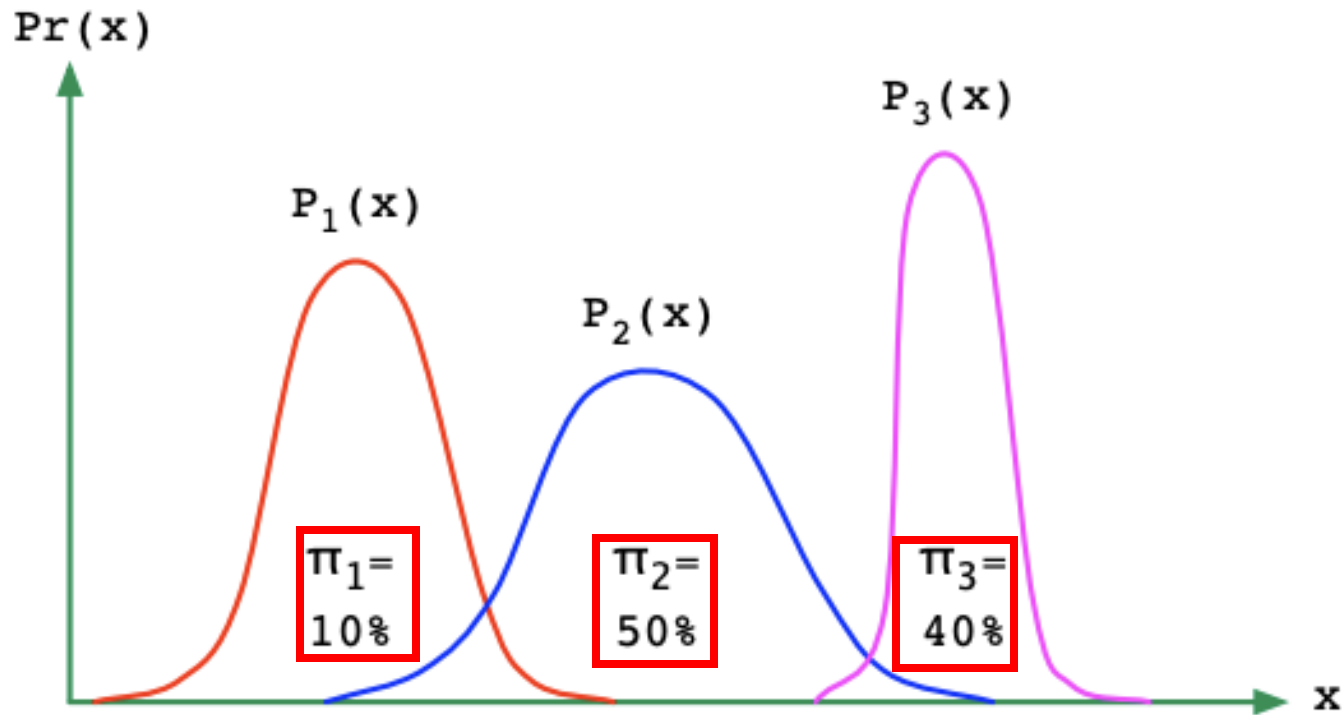
Q: how to classify a new data?

Generative models



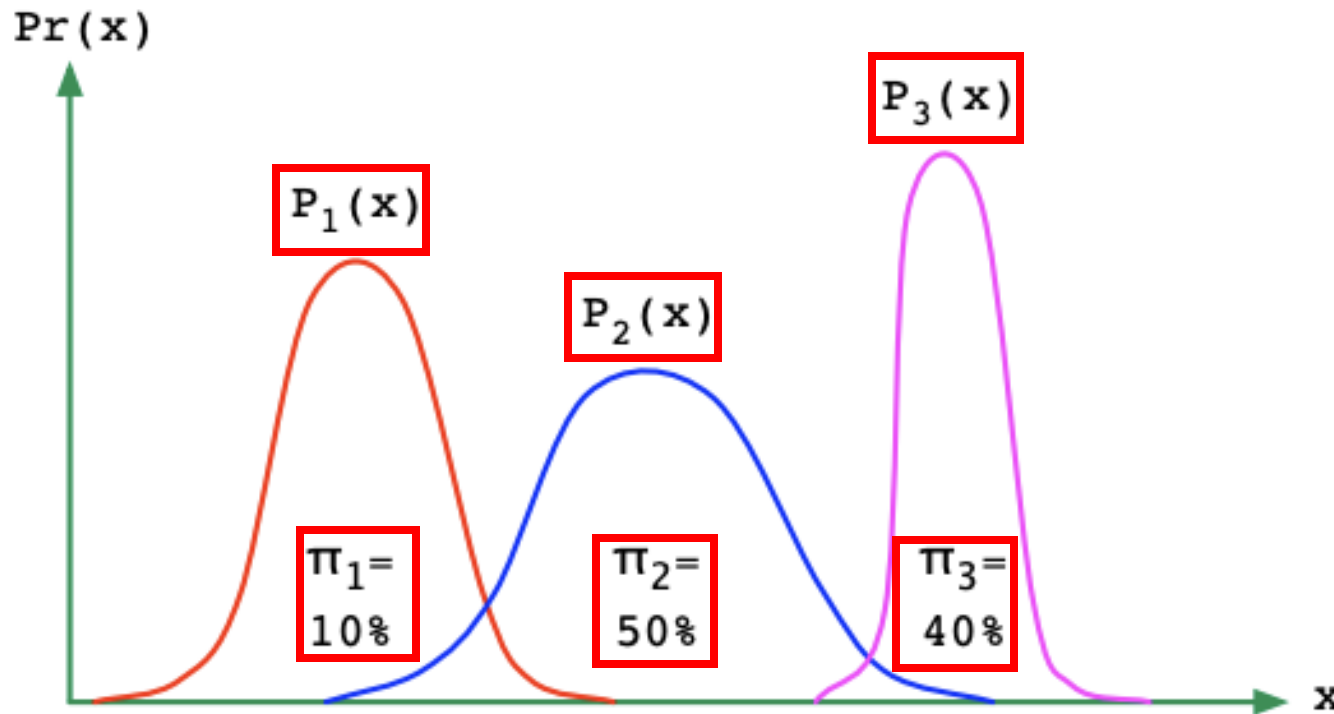
$$\Pr(x, y) = \Pr(y)\Pr(x|y) = \pi_y P_y(x).$$

Generative models



$$\text{Pr}(x, y) = \boxed{\text{Pr}(y)} \text{Pr}(x|y) = \boxed{\pi_y} P_y(x).$$

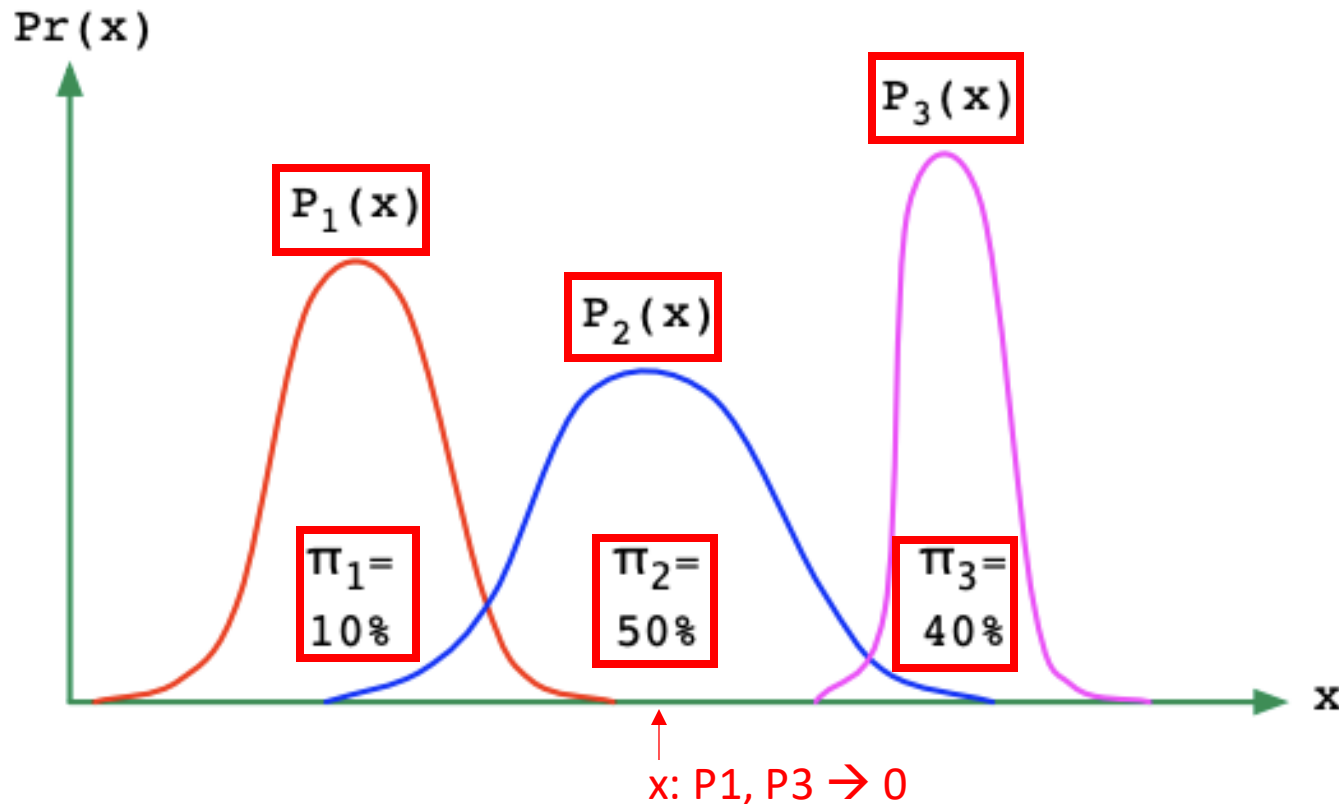
Generative models



$$\text{Pr}(x, y) = \text{Pr}(y) \text{Pr}(x|y) = \pi_y P_y(x).$$

Pick the label y making $P(x, y)$ largest

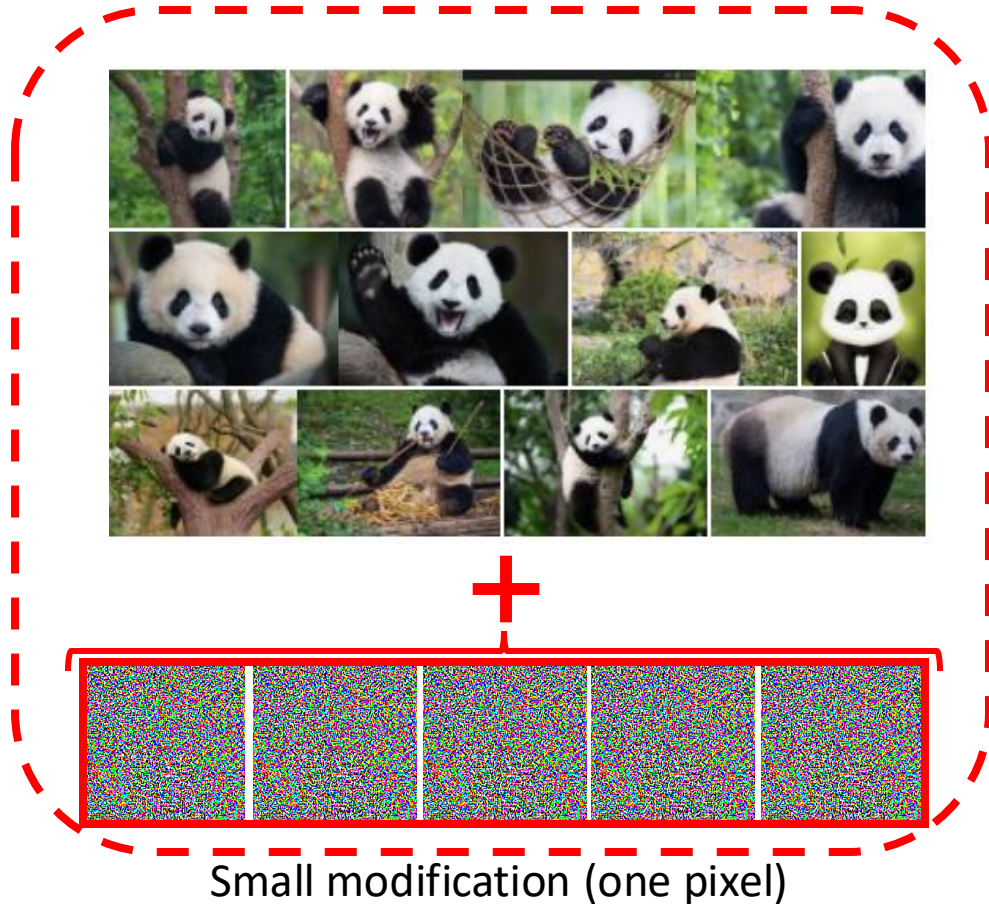
Generative models



$$\text{Pr}(x, y) = \text{Pr}(y) \text{Pr}(x|y) = \pi_y P_y(x).$$

Pick the label y making $P(x, y)$ largest

Adversarial learning and generative models



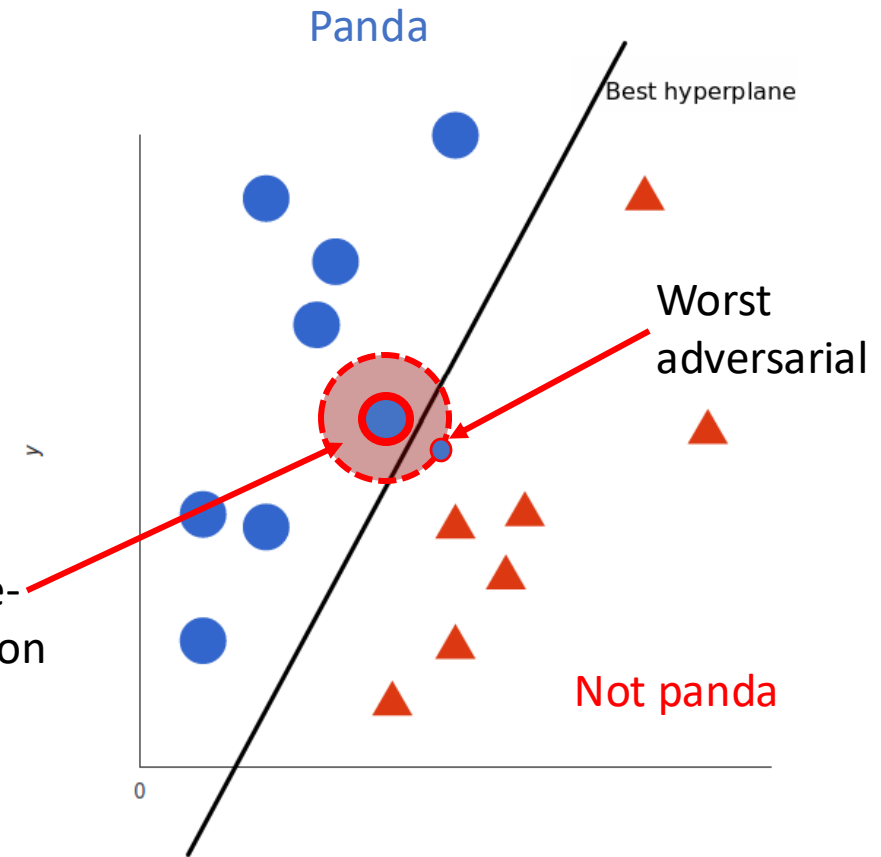
ML model for
panda recognition

All possible one-
pixel modification

0~255
↑

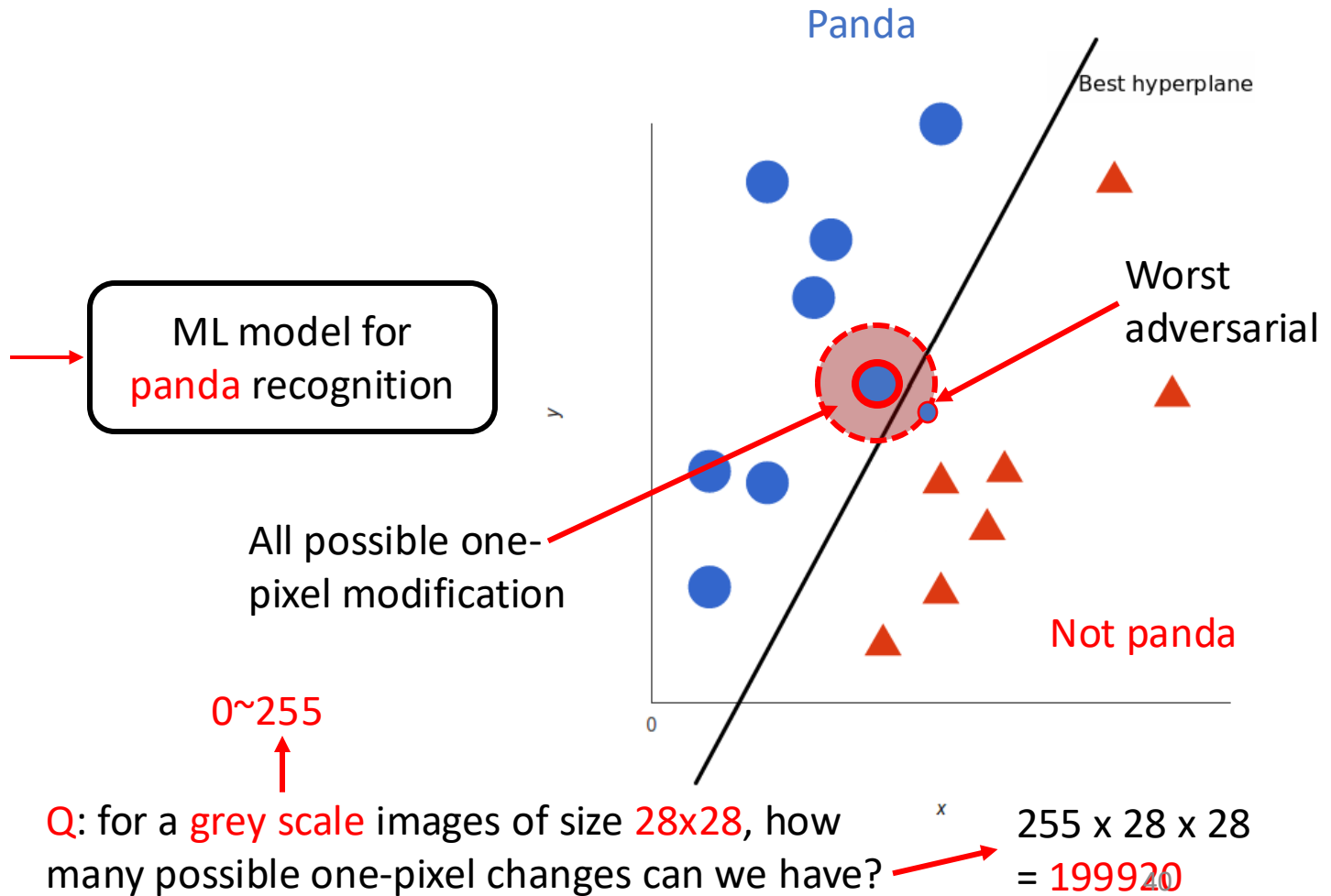
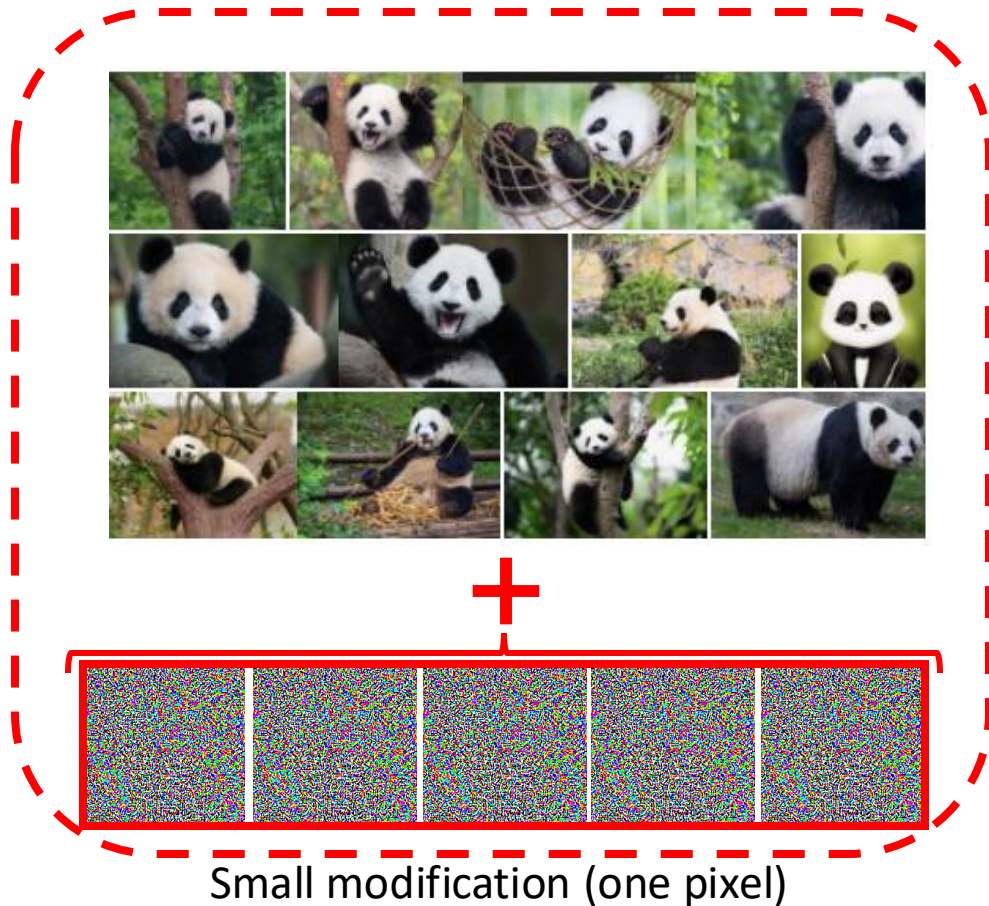
Q: for a **grey scale** images of size **28x28**, how many possible one-pixel changes can we have?

$255 \times 28 \times 28 = 199920$



Adversarial learning and generative models

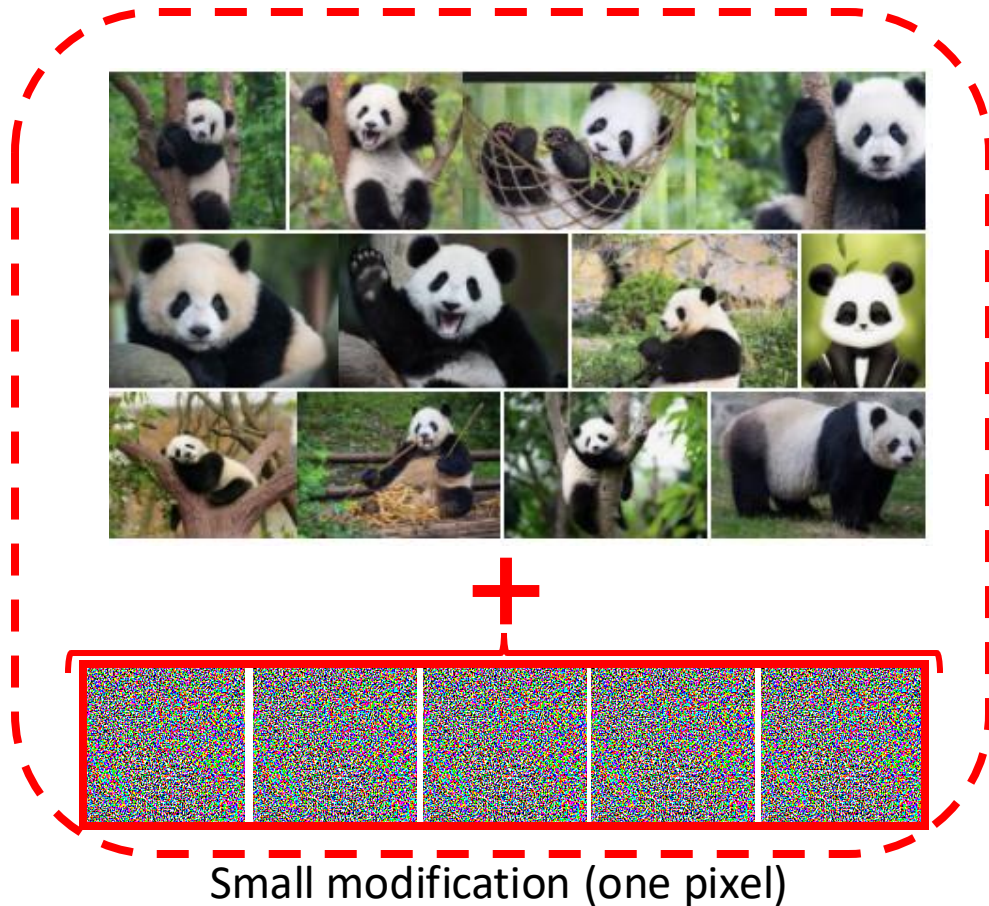
Limit: additive noise is only one way to generate adversarial data



Adversarial learning and generative models

Limit: additive noise is only one way to generate adversarial data

Q: can generative models help?



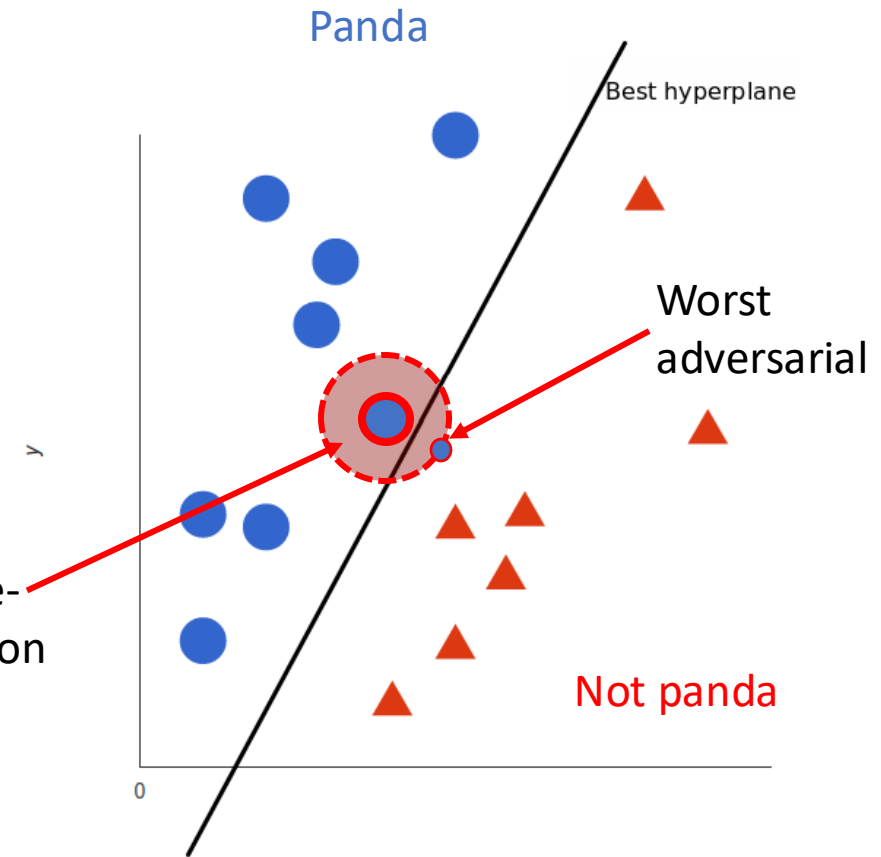
ML model for panda recognition

All possible one-pixel modification

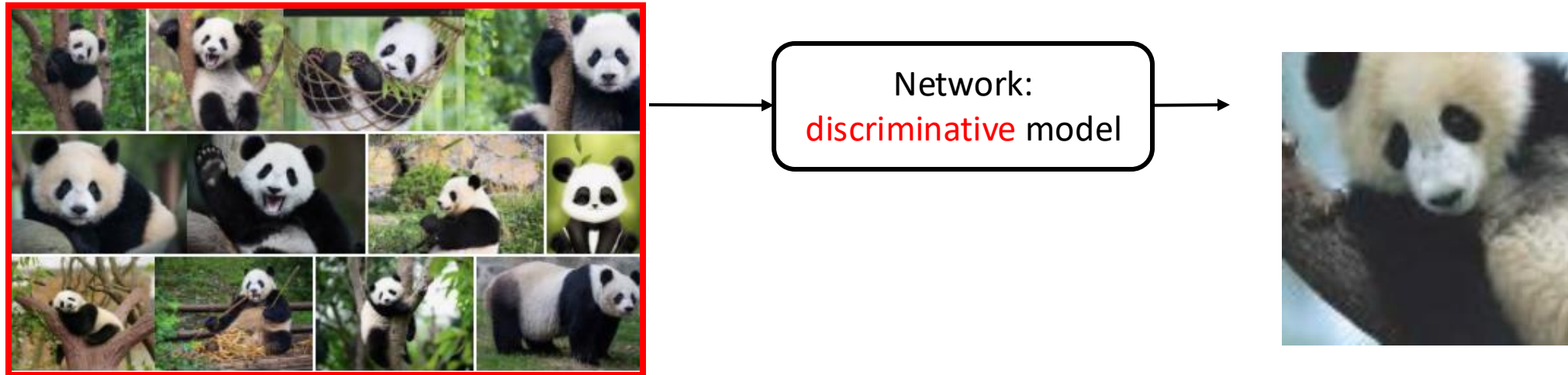
0~255

Q: for a **grey scale** images of size **28x28**, how many possible one-pixel changes can we have?

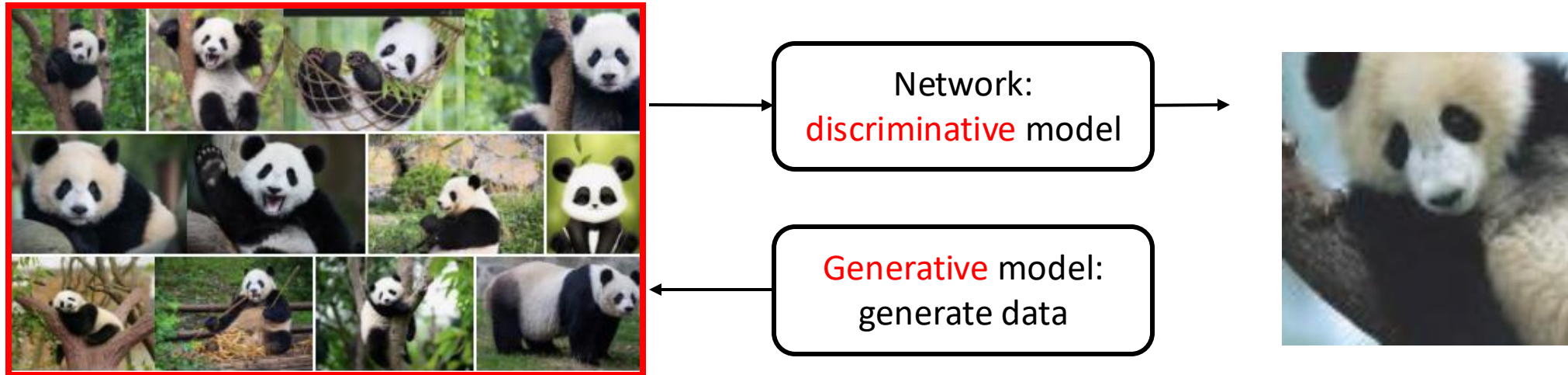
$255 \times 28 \times 28 = 199920$



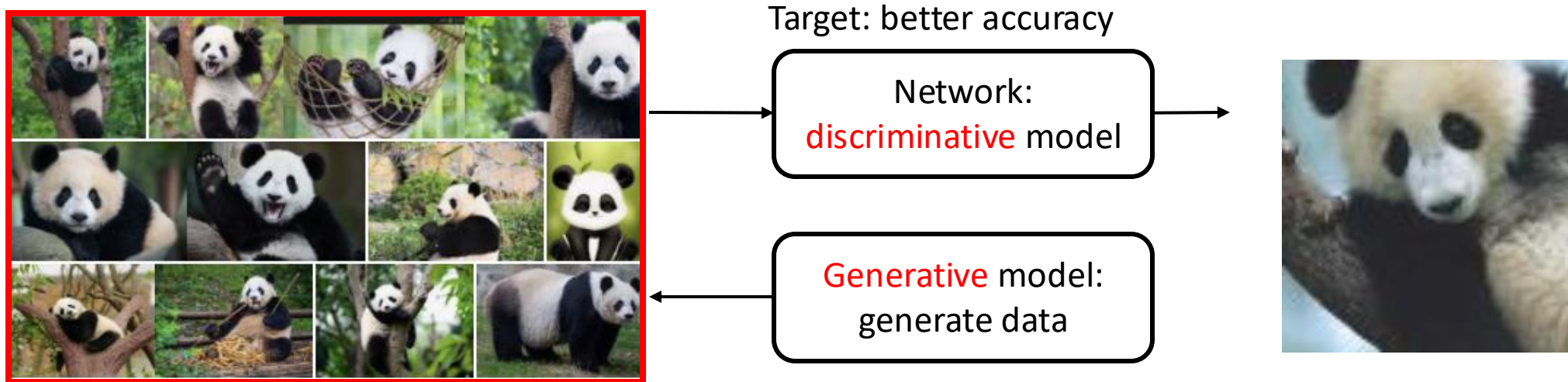
Generative adversarial networks



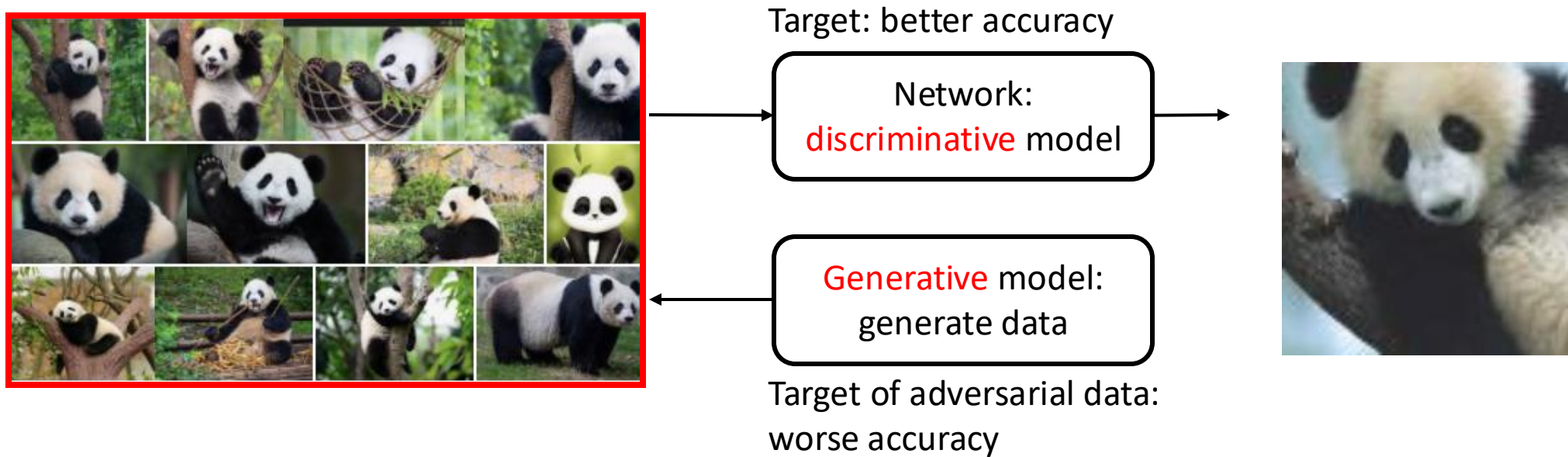
Generative adversarial networks



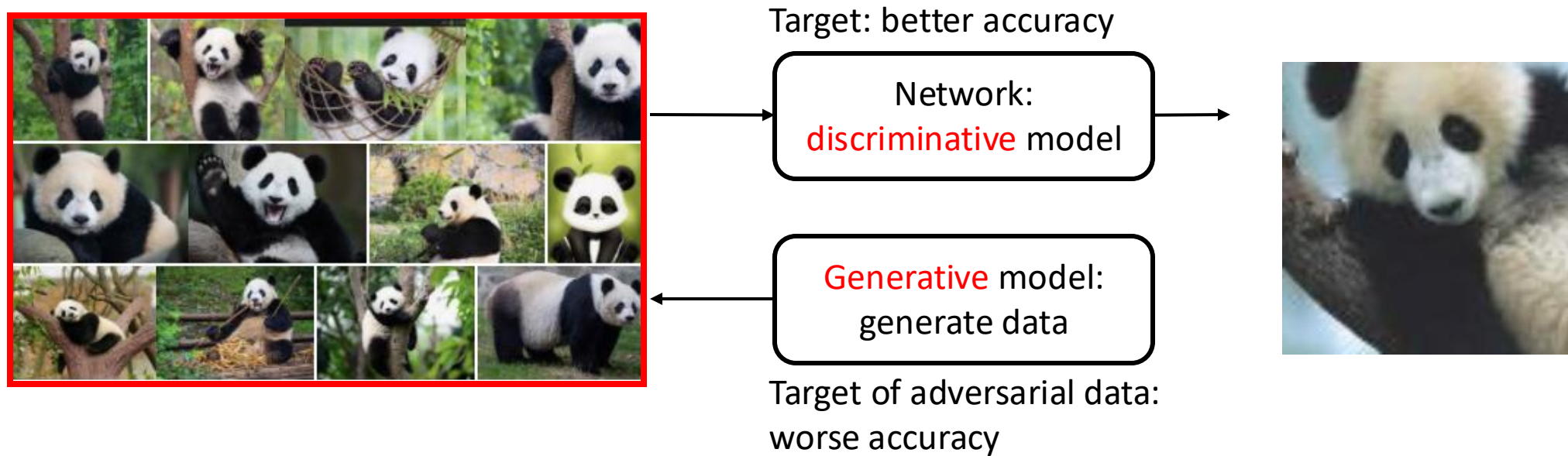
Generative adversarial networks



Generative adversarial networks

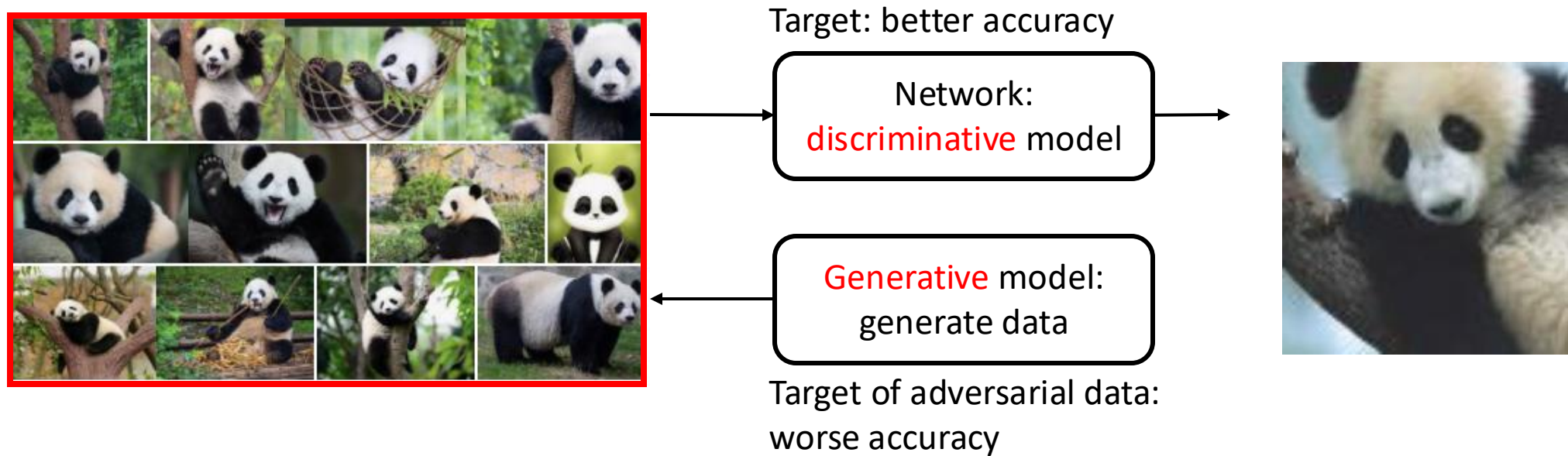


Generative adversarial networks



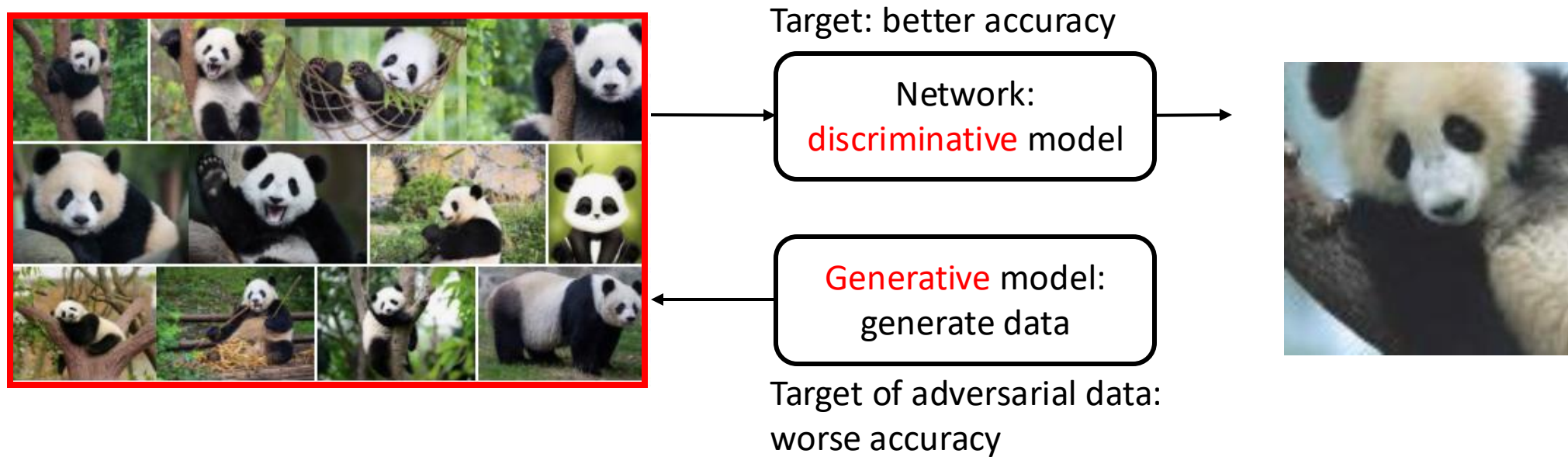
$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))] .$$

Generative adversarial networks



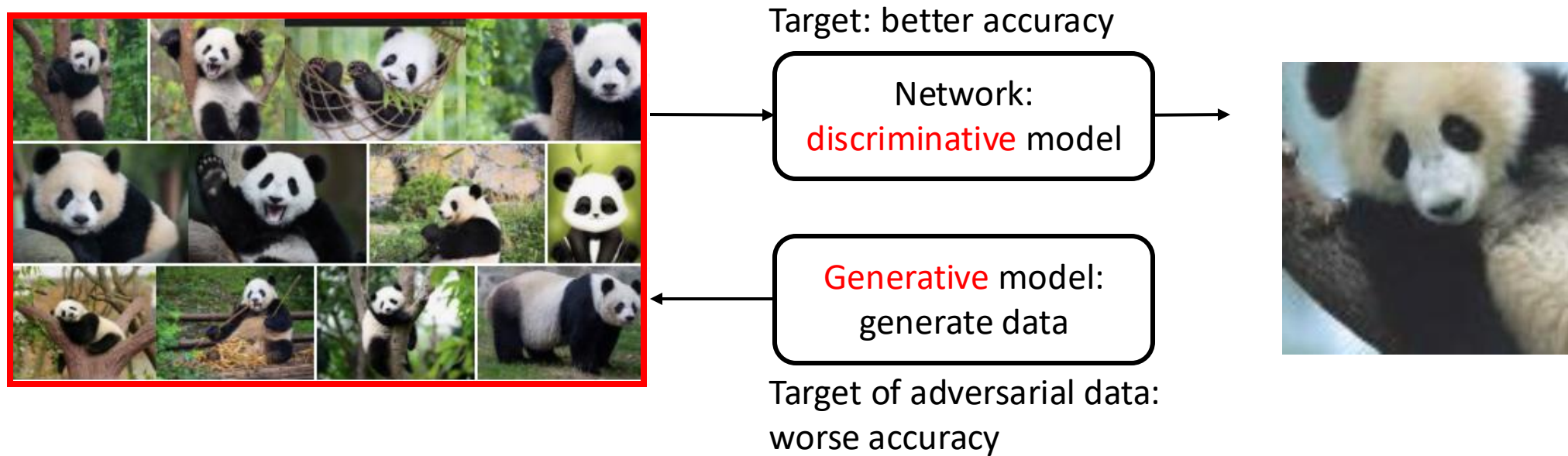
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Generative adversarial networks



$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))].$$

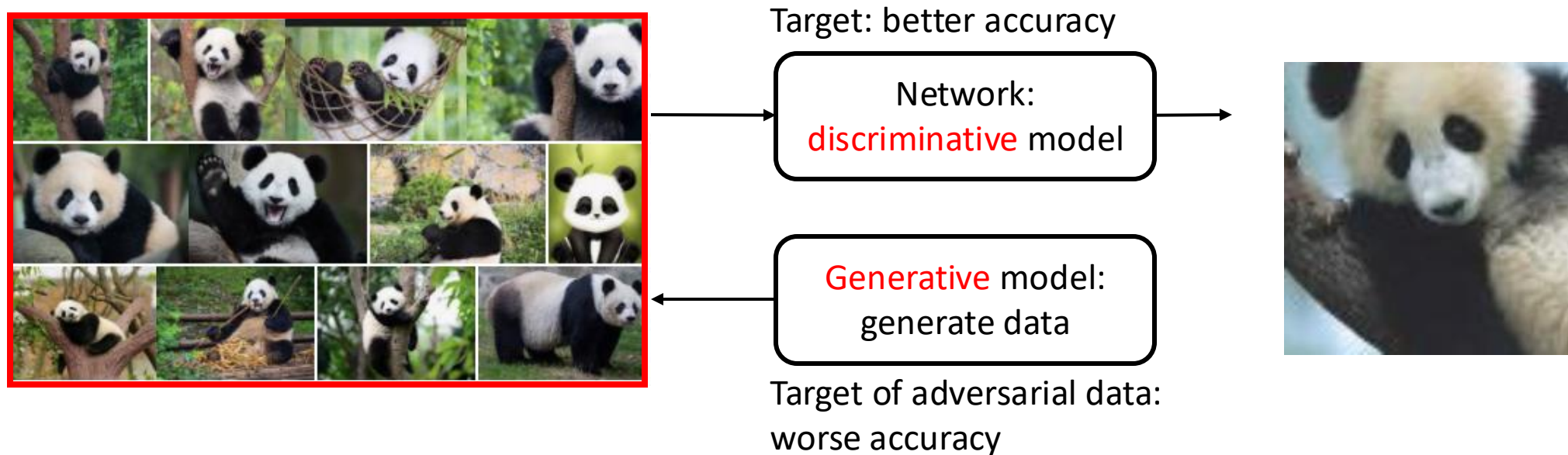
Generative adversarial networks



$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))]$$

Use original training data

Generative adversarial networks

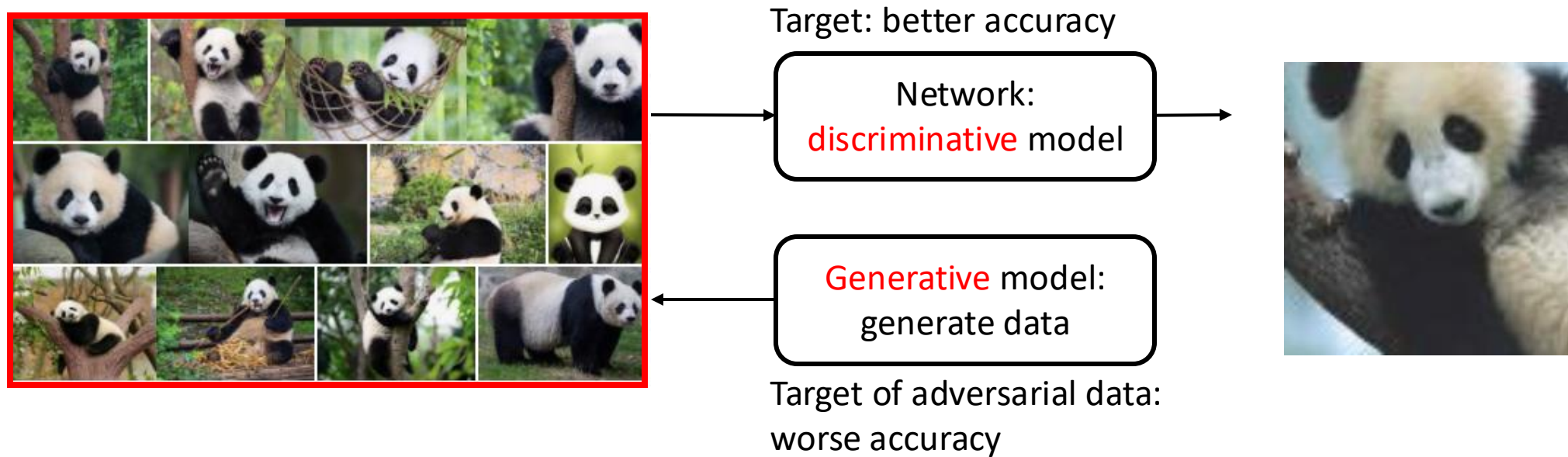


$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} \log D(\mathbf{x}) + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))].$$

Use original training data

Maximum likelihood estimation

Generative adversarial networks



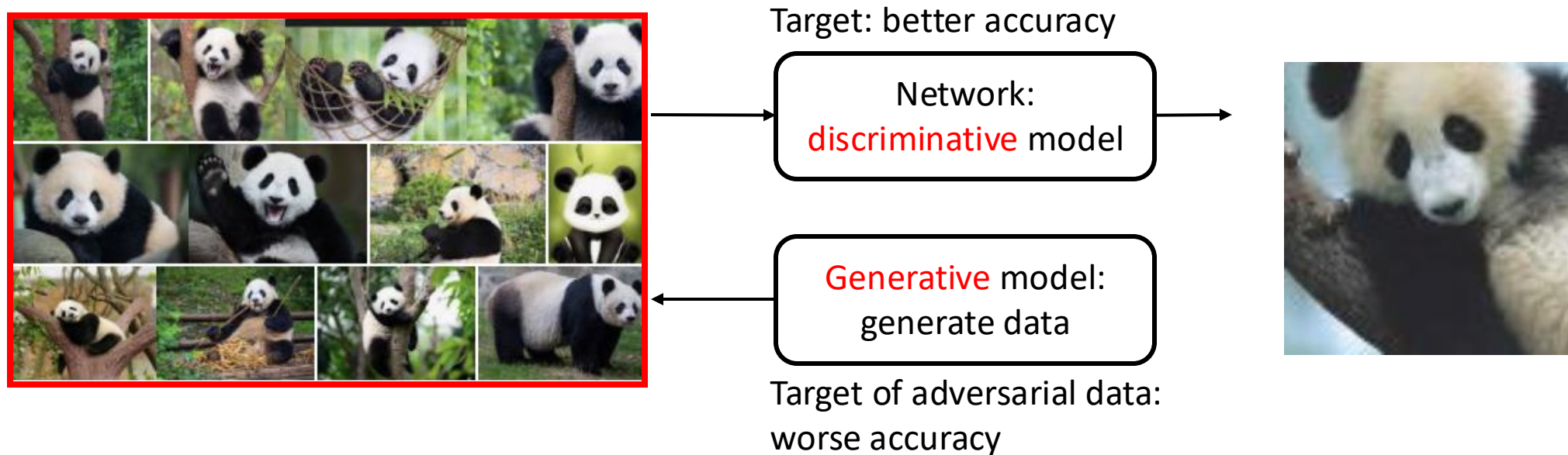
$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))].$$

Use original training data

Input noise variable

Maximum likelihood estimation

Generative adversarial networks



$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))].$$

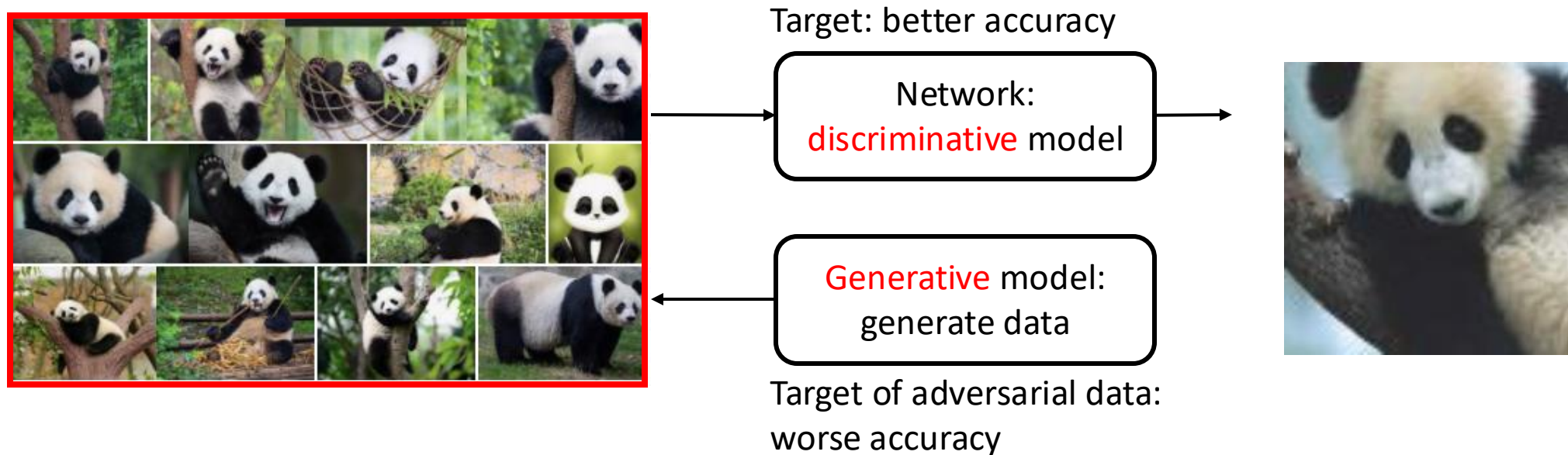
Use original training data

Maximum likelihood estimation

Input noise variable

Use **generated data** (from noise)

Generative adversarial networks



$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))].$$

Use original training data

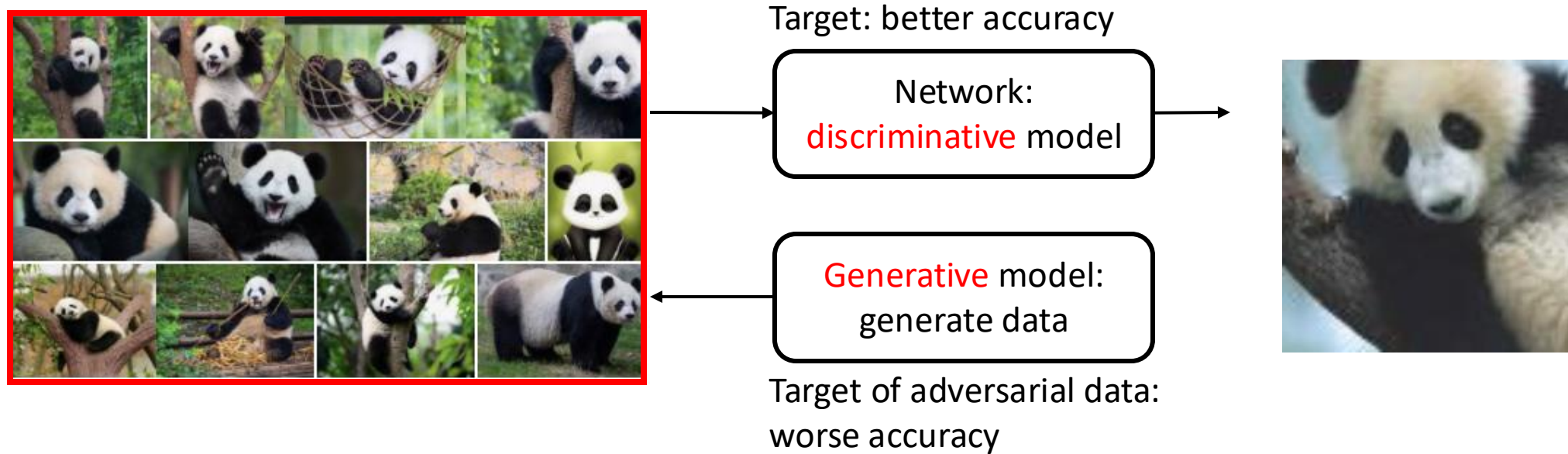
Maximum likelihood estimation

Input noise variable

Use generated data (from noise)

Generated data → discriminator

Generative adversarial networks



$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))].$$

MLE of $-D(\text{adv.})$

Use original training data

Maximum likelihood estimation

Input noise variable

Use generated data (from noise)

Generated data \rightarrow discriminator

Generative adversarial networks

